
Experiments in Transient Nonlinear Energy Pumping in Vibrating Mechanical Systems

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Aim of this Work

- To develop and implement a new approach to passively control vibration and shock in flexible structures.
- This technique is based on passively channeling vibrational energy into nonlinear energy sinks (NESs), where it is confined and dissipated.

Related Technologies

- Current methods

 - Damping

 - Linear vibration absorbers

 - Active and semi-active control

 - Redesign of structure

- Proposed method

 - Nonlinear energy sink (NES)

Originality of Our Approach

- NESs are capable of passively absorbing and dissipating **broadband** (transient) **disturbances**
- NESs can **nonlinearly interact with a series of structural modes**, extracting a significant amount of energy from each before engaging the next
- In contrast to previous work on nonlinear vibration absorbers, **general transient, strongly nonlinear responses are considered**. The techniques developed directly address the transient problem as well as the steady state.

Practicality of the NES

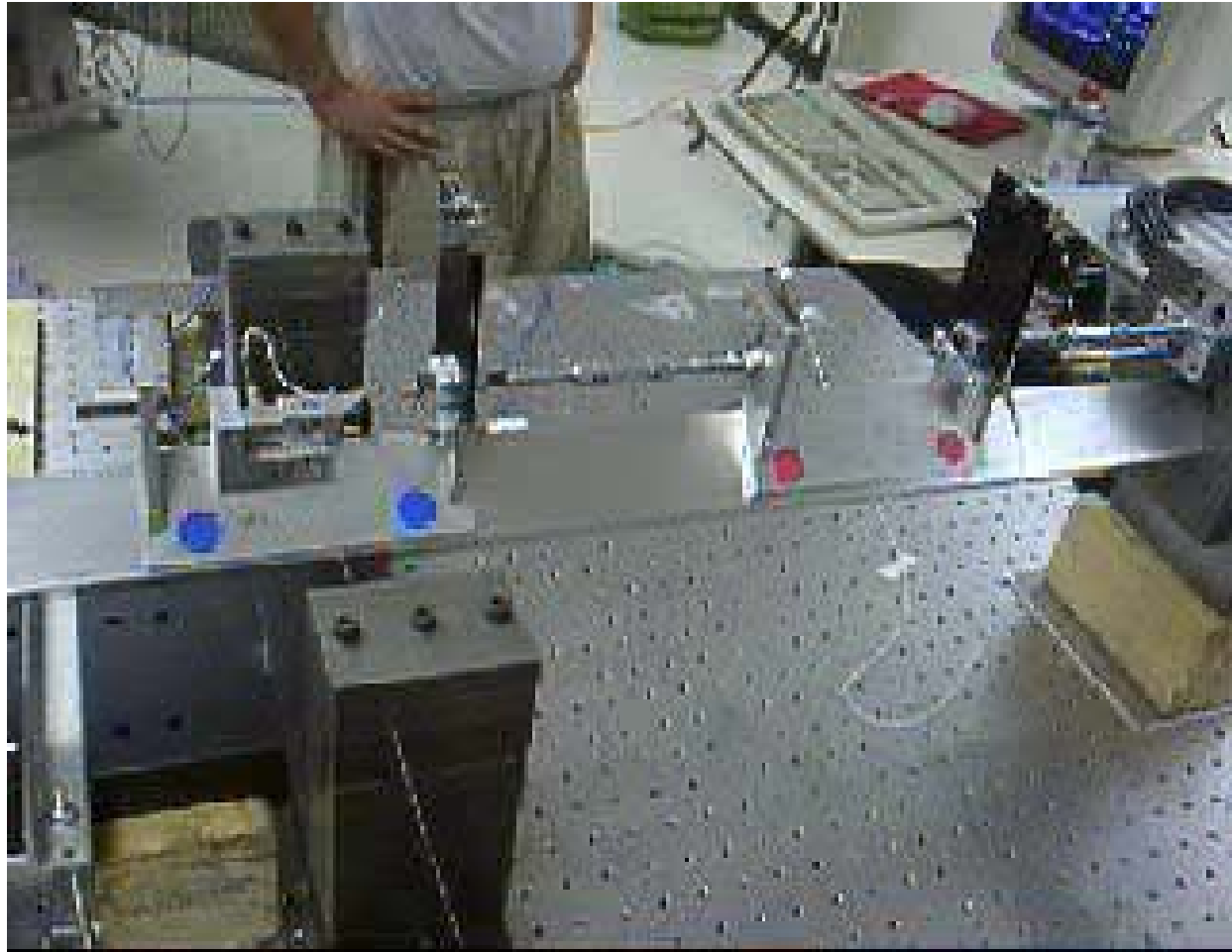
- Modular and, hence, can be connected to existing structures with minimal modification
- Lightweight and of simple design
- Passive and does not require power to operate
- Inexpensive, especially when compared to structural redesign
- Although they are local attachments, NESs can affect the global structural dynamics

Introduction

- Energy pumping is the passive, one-way, rapid and irreversible transfer of energy from a vibrating main structure to an attached nonlinear energy sink
- The main structure can be either linear or nonlinear, while the coupling with the NES is assumed to be linear and weak
- The NES possesses essential (nonlinearizable) stiffness nonlinearity

Early Experiments

- A system where the NES possesses no damper



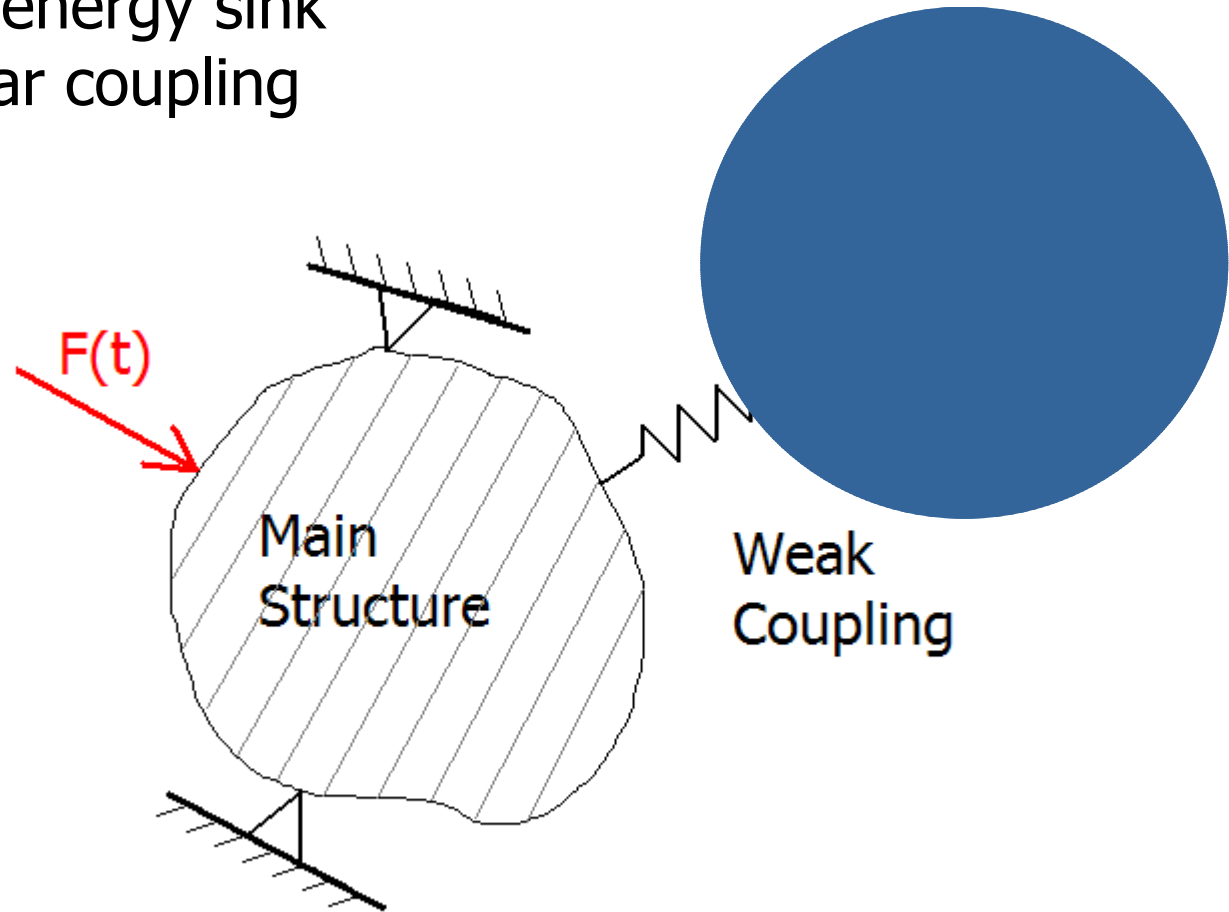
Early Experiments

- A damper has been added to the NES



Basic Configuration

- Linear primary structure
- Nonlinear energy sink
- Weak linear coupling



Theoretical Basis

- Consider an (N+1) DOF linear main structure coupled to an essentially nonlinear NES. In terms of modal coordinates the structural response at the point of attachment O is expressed in the form

$$y_0(t) = \sum_{k=0}^N \phi_0^{(k)} a_k(t)$$

where $\phi_0^{(k)}$ denotes the element at position O of the k-th mass-normalized eigenvector of the uncoupled structure (with $\varepsilon=0$), and $a_k(t)$ represents the k-th modal amplitude of the structure. (1)

Theoretical Basis

- Then, the equations of motion of the system are expressed as

$$\ddot{\mathbf{v}}(t) + \mathbf{C}\mathbf{v}^3(t) + \varepsilon\lambda\dot{\mathbf{v}}(t) + \varepsilon\left(\mathbf{v} - \sum_{k=0}^N \phi_0^{(k)}\mathbf{a}_k(t)\right) = 0$$

$$\ddot{a}_m(t) + \omega_m^2 a_m(t) + \varepsilon\lambda\dot{a}_m(t) + \varepsilon\left(\sum_{k=0}^N \phi_0^{(k)}\phi_0^{(m)} a_k(t) - \phi_0^{(m)}\mathbf{v}(t)\right) = 0, \\ m = 0, 1, \dots, N \quad (2)$$

- Consider the nonlinear resonance interactions between the NES and an individual mode, say the zero-th one, of the main structure

Theoretical Basis: NNMs

- Dynamics of the unforced, undamped system

$$\ddot{\mathbf{v}}(t) + \mathbf{C}\mathbf{v}^3(t) + \varepsilon \left(\mathbf{v}(t) - \phi_0^{(0)}\mathbf{a}_0(t) - \sum_{k=1}^N \phi_0^{(k)}\mathbf{a}_k(t) \right) = 0$$

$$\ddot{a}_0(t) + \omega_0^2 a_0(t) + \varepsilon \left(\phi_0^{(0)2} a_0(t) - \phi_0^{(0)} \mathbf{v}(t) + \sum_{k=1}^N \phi_0^{(k)} \phi_0^{(0)} a_k(t) \right) = 0$$

$$\ddot{a}_m(t) + \omega_m^2 a_m(t) + \varepsilon \left(\sum_{k=0}^N \phi_0^{(k)} \phi_0^{(m)} a_k(t) - \phi_0^{(m)} \mathbf{v}(t) \right) = 0 ,$$

$$m = 1, \dots, N$$

Theoretical Basis: NNMs

The physical NNM oscillations of the NES and the point of attachment of the structure are approximated as

$$v(t) = \frac{A_v}{\omega_0} \sin(\omega_0 t + \gamma_v(t) + O(\varepsilon^2)) + O(\varepsilon)$$

$$y_0(t) = \phi_0^{(0)} \frac{A_0}{\omega_0} \sin(\omega_0 t + \gamma_0(t) + O(\varepsilon^2)) + O(\varepsilon)$$

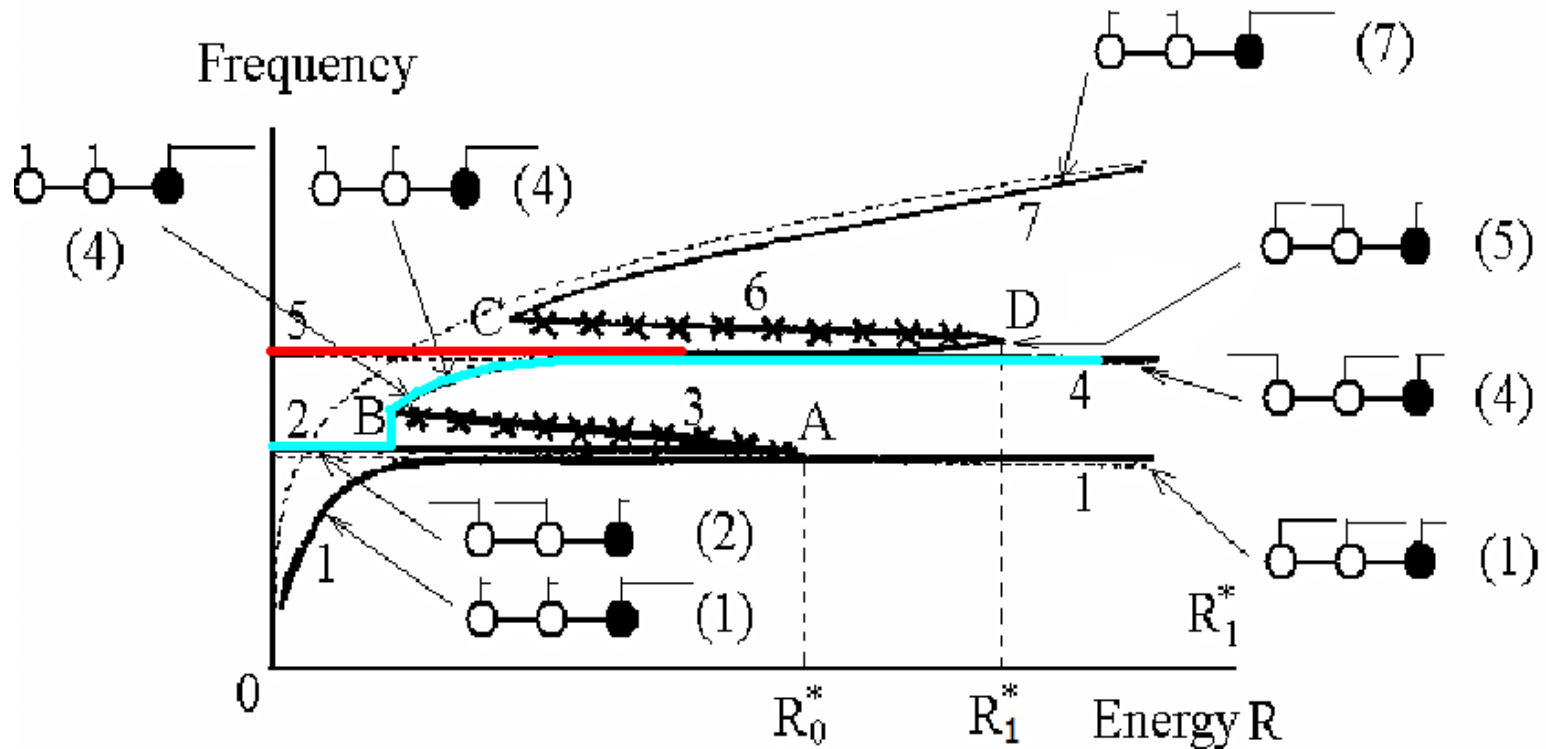
$$\dot{\gamma}_v = \dot{\gamma}_0 = \frac{\varepsilon}{2\omega_0} \left[\phi_0^{(0)2} - \phi_0^{(0)} \frac{A_v}{A_0} \right]$$

with frequency

$$\Omega_0 \approx \omega_0 + \dot{\gamma}_v = \omega_0 + \frac{\varepsilon}{2\omega_0} \left[\phi_0^{(0)2} - \phi_0^{(0)} \frac{A_v}{A_0} \right]$$

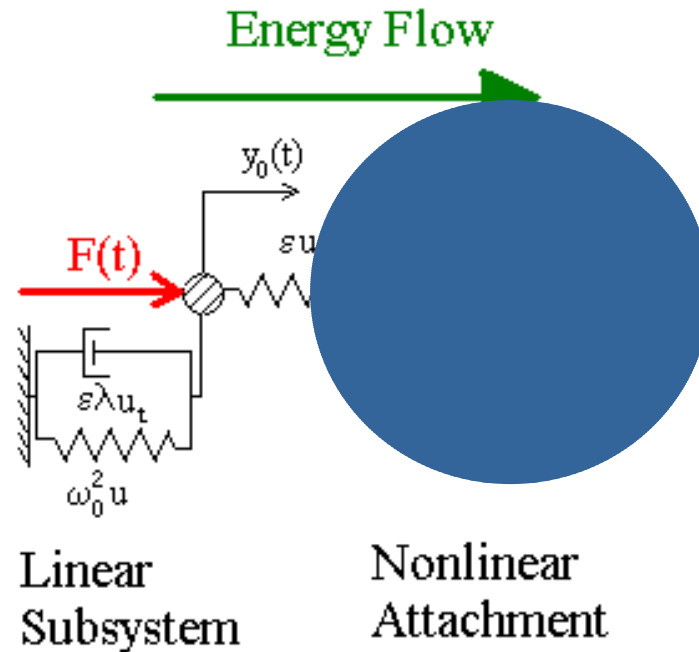
Theoretical Basis

Schematically, we synthesize local results, using the physical energy R as the independent variable.



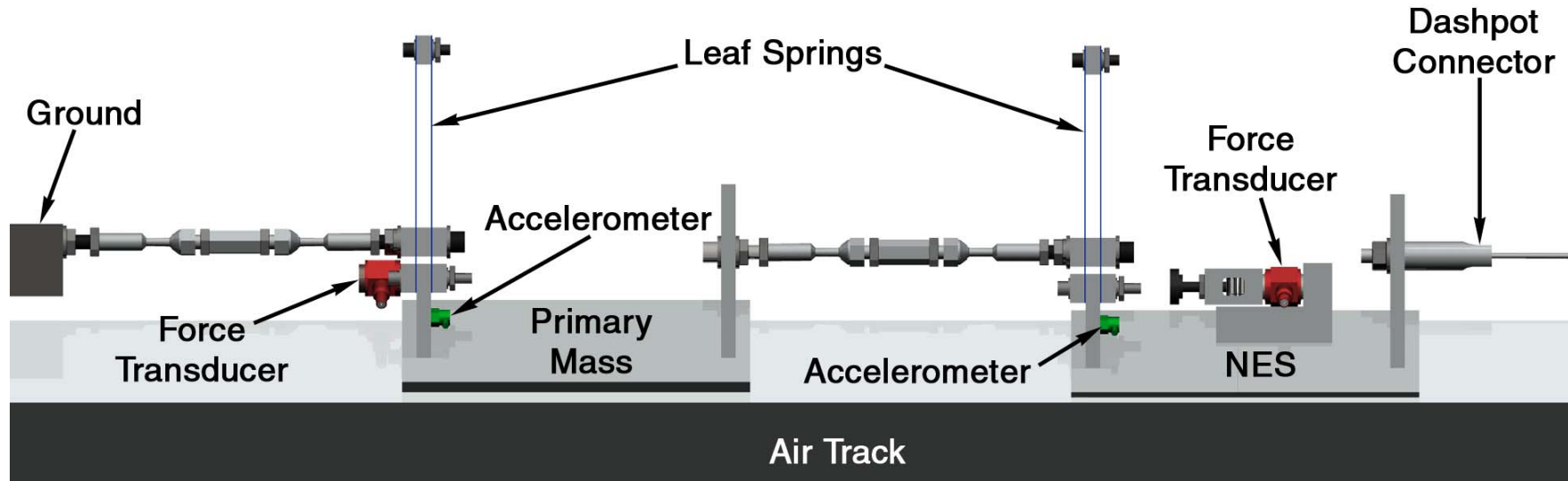
Experimental System: SDOF + NES

Our first experiments were on a 2-DOF system: an SDOF primary structure connected to an NES

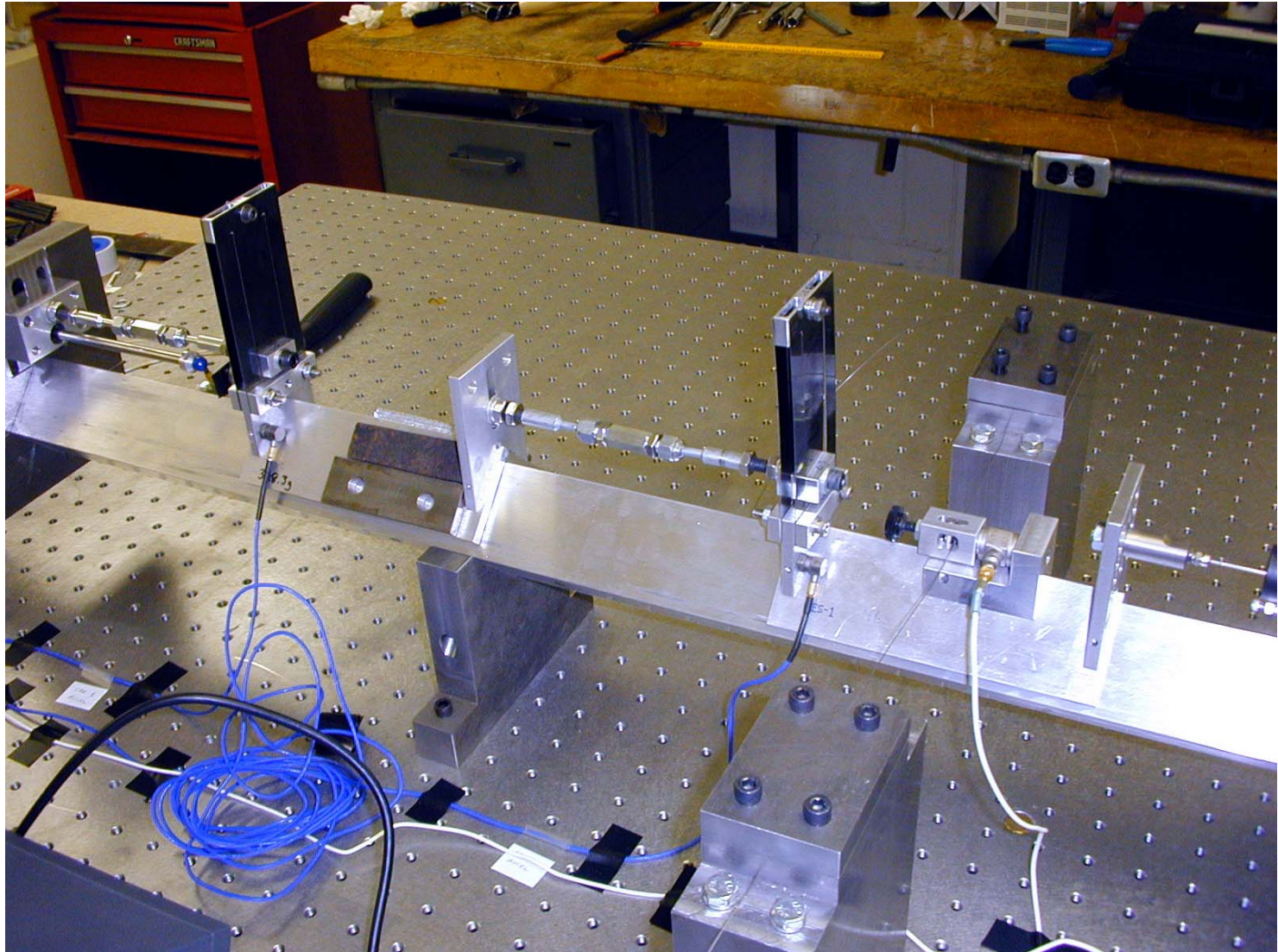


Experimental System: SDOF + NES

- Two "cars" ride on a 1-D air track
- Applied force and response acceleration are measured directly



Experimental System: SDOF + NES



Experimental System: SDOF + NES

■ Linear subsystem

$$M = 0.834 \text{ kg}, \quad K = 993 \text{ N/m}, \quad \varepsilon\lambda = 0.129 \text{ Nsec/m}$$

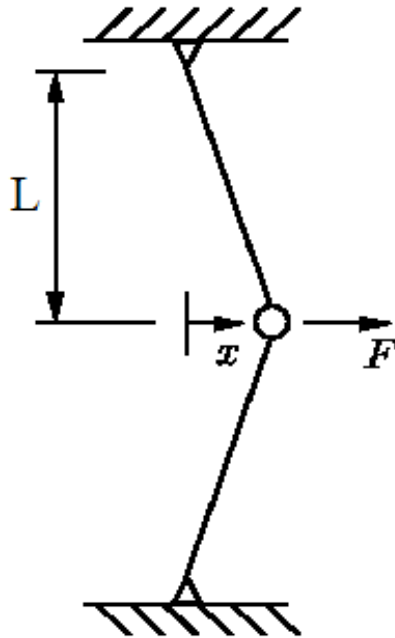
$$\omega_0 = 35.63 \text{ rad/sec} \quad \zeta = 2.3 \times 10^{-3}$$

■ Nonlinear energy sink

$$m = 0.393 \text{ kg}, \quad \varepsilon = 114 \text{ N/m}, \quad \varepsilon c = 0.454 \text{ Nsec/m}$$

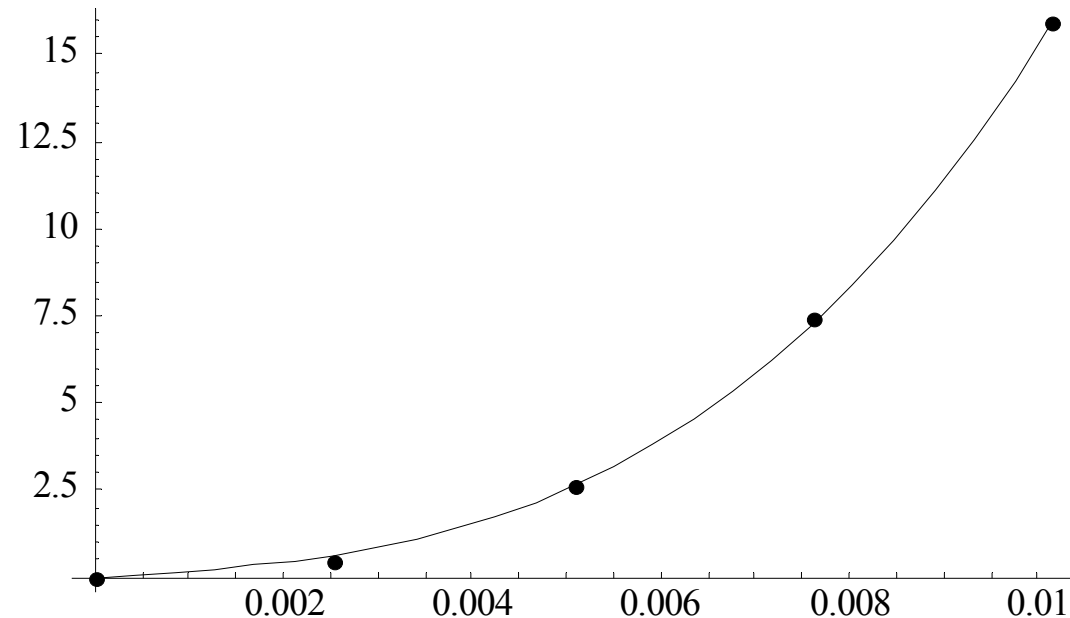
Experimental System

- Nonlinear spring



$$F = \frac{EA}{L^3} x^3 + O(x^5)$$

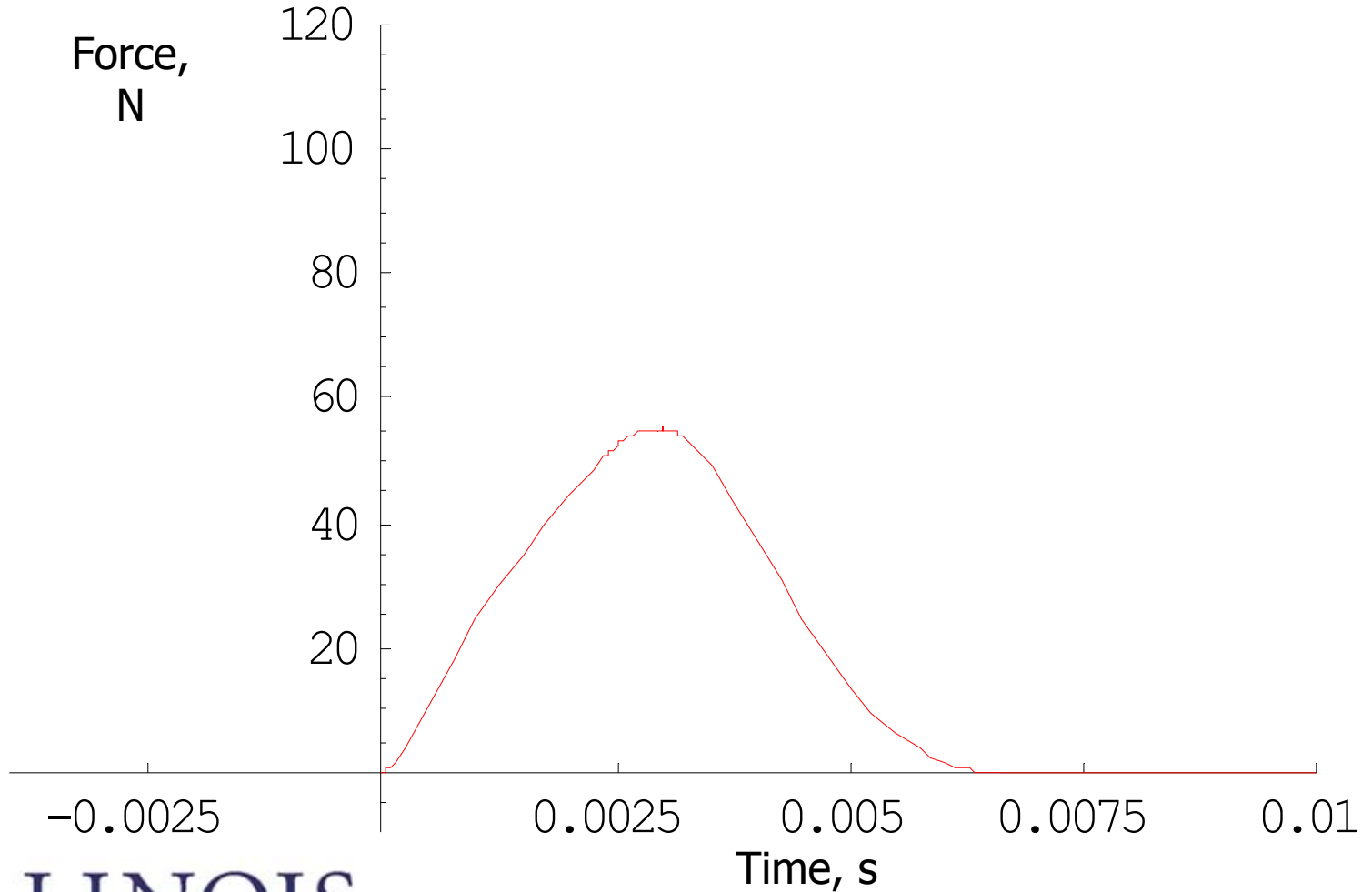
Fitted polynomial has 1st and 3rd order terms.



$$f(x) = 166x + 1.36 \times 10^7 x^3$$

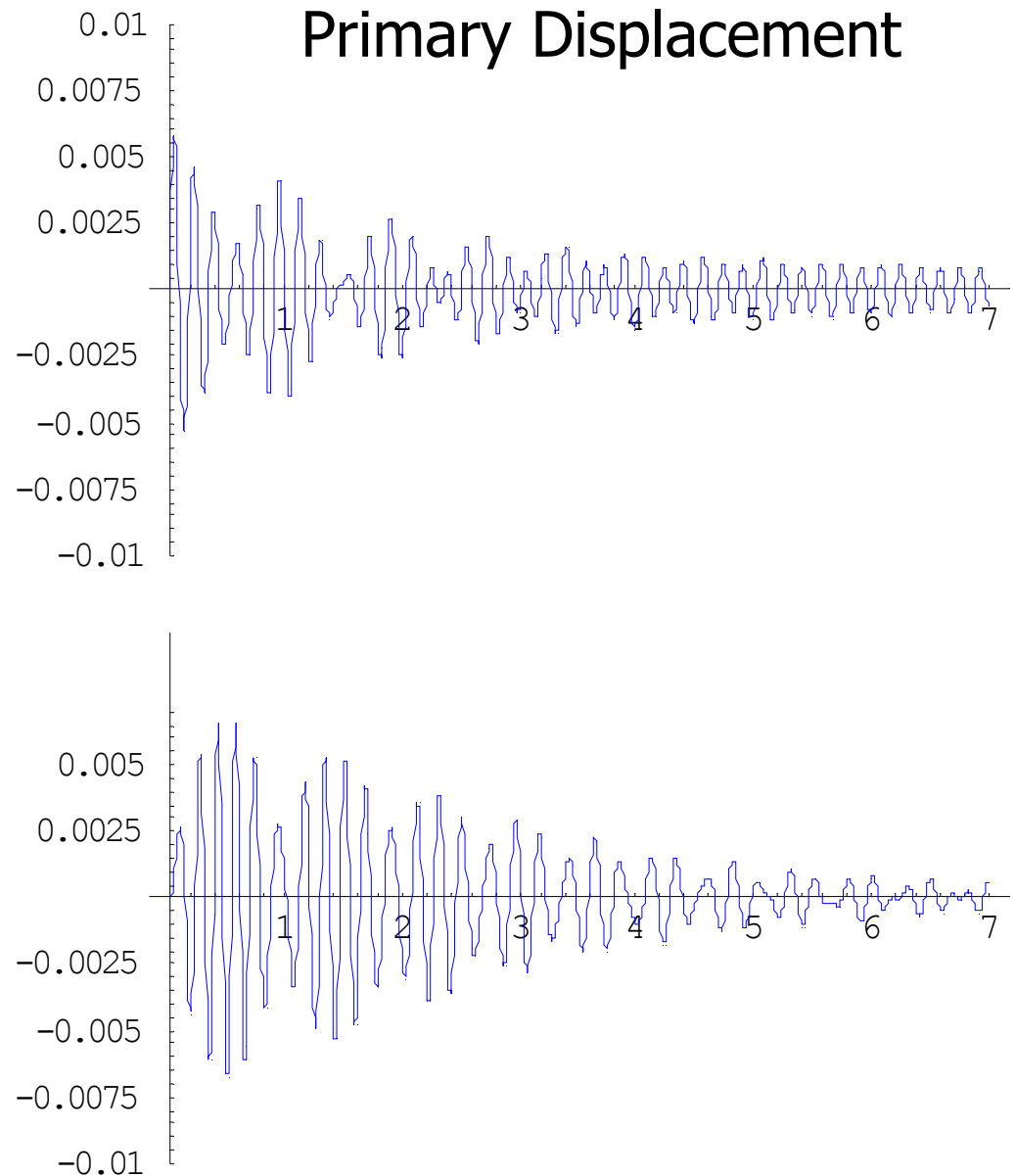
Measured Data

- Typical "strong" force pulse



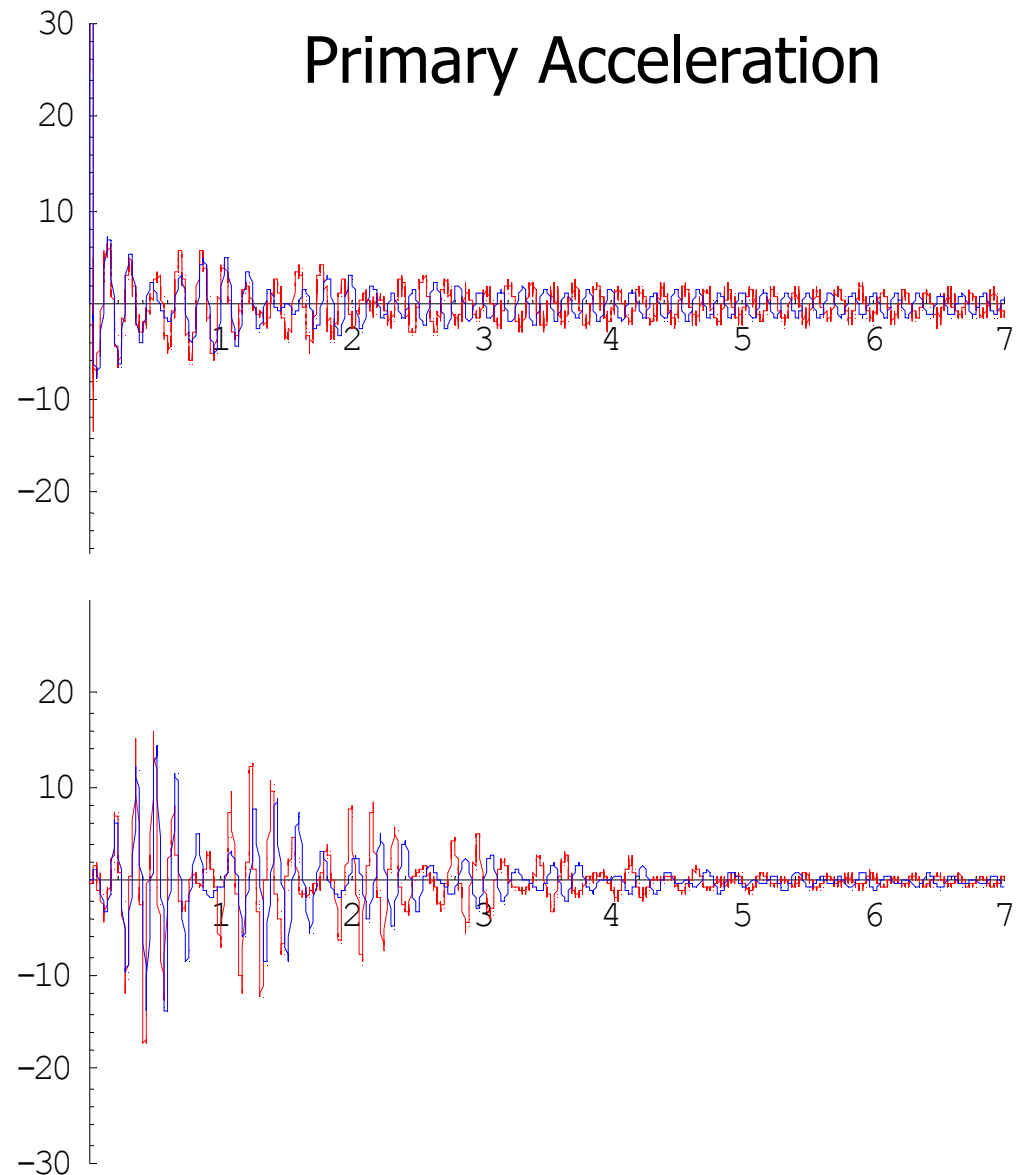
Simulated Response

Results of numerical integration using measured applied force as input



Measured Response & Simulation

- Primary and NES accelerations
- Good agreement of amplitude
- Good agreement of “slow” response
- Distinct transient resonance captures
- Results were repeatable



Measure of Energy Pumping

- Total energy input

$$E_i(t) = \int_0^t F(\tau) \dot{y}(\tau) d\tau$$

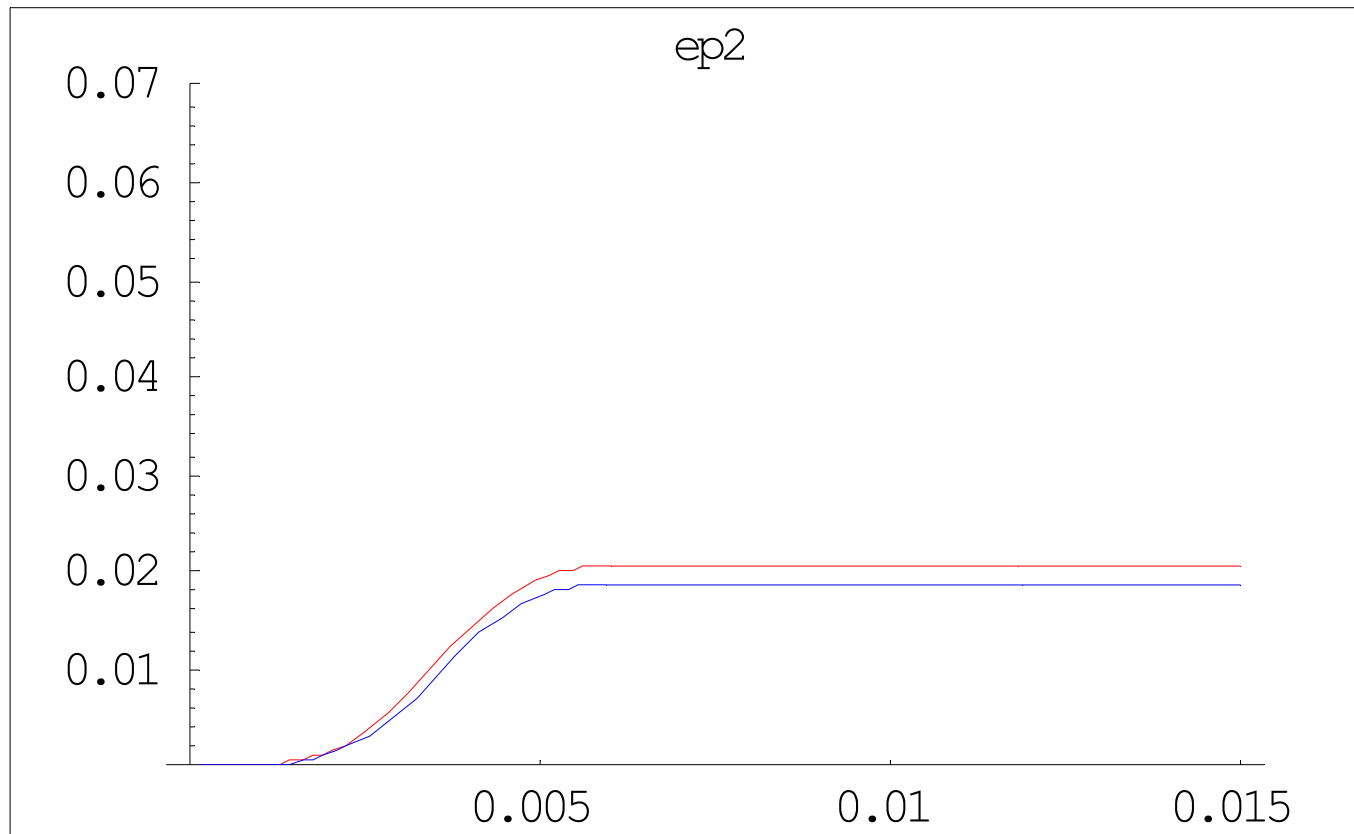
- Energy dissipated in sink dashpot

$$E_{\text{NES}}(t) = \frac{\varepsilon c}{E_i(t_{\text{max}})} \int_0^t \dot{v}^2(\tau) d\tau$$

- We compute the normalized dissipation in the NES as a function of time

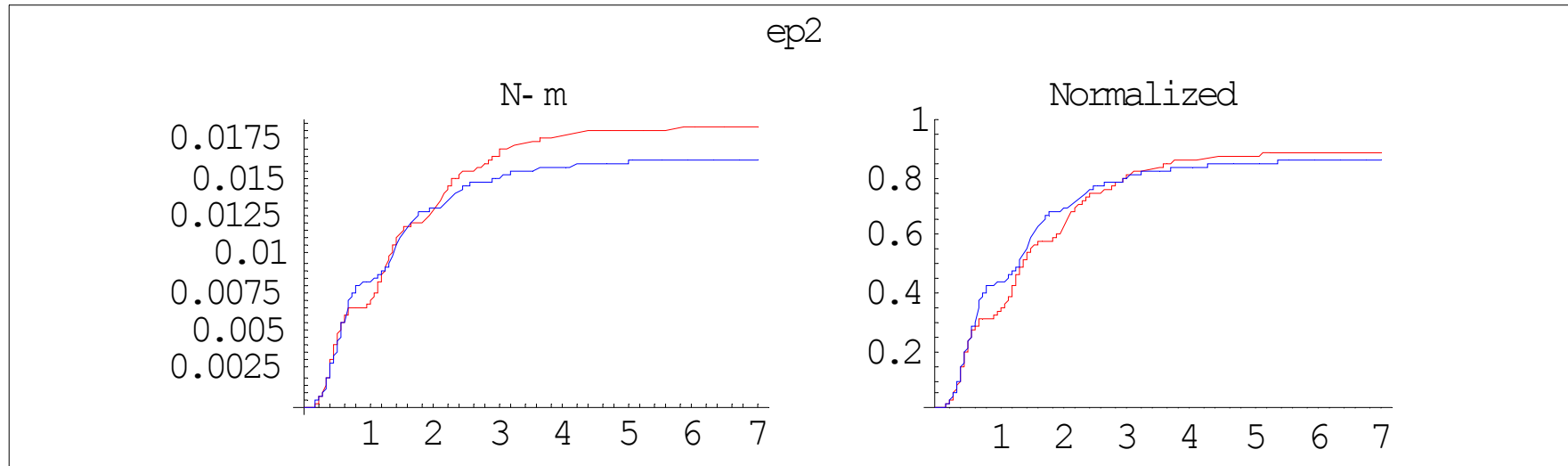
Measure of Energy Pumping

- All energy input occurs in a few msec.



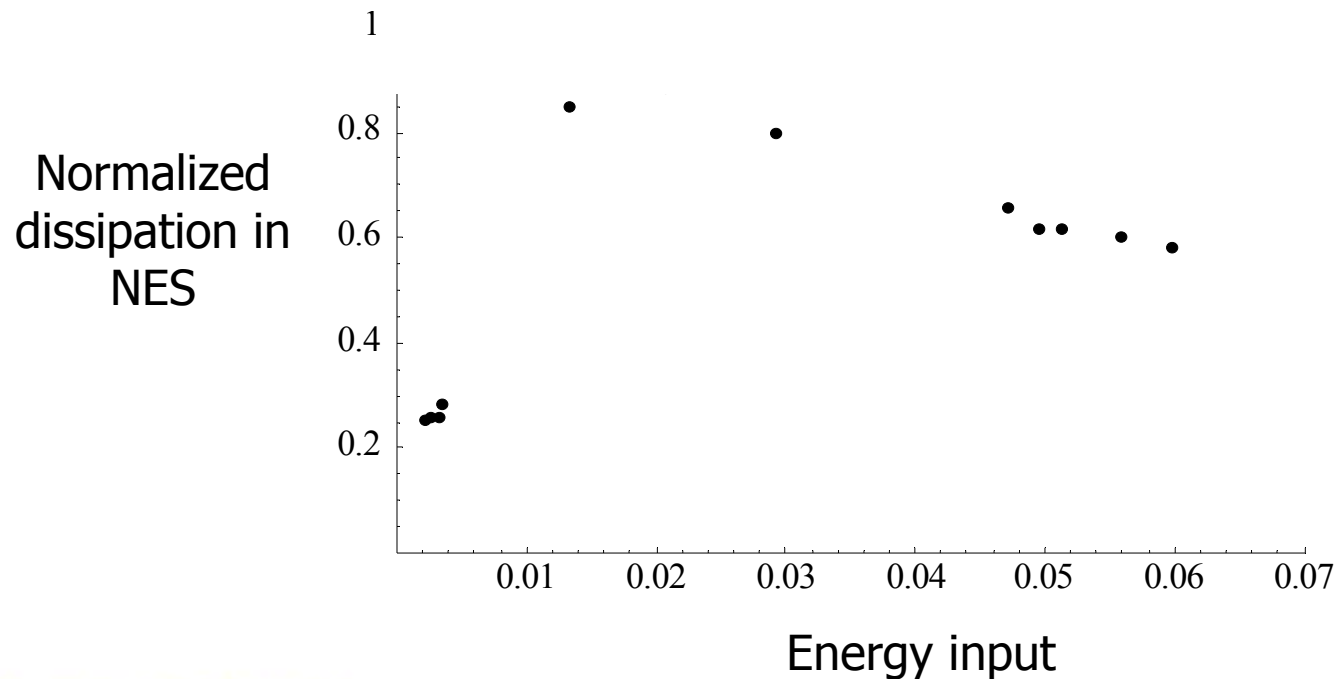
Measure of Energy Pumping

- Dissipation in NES



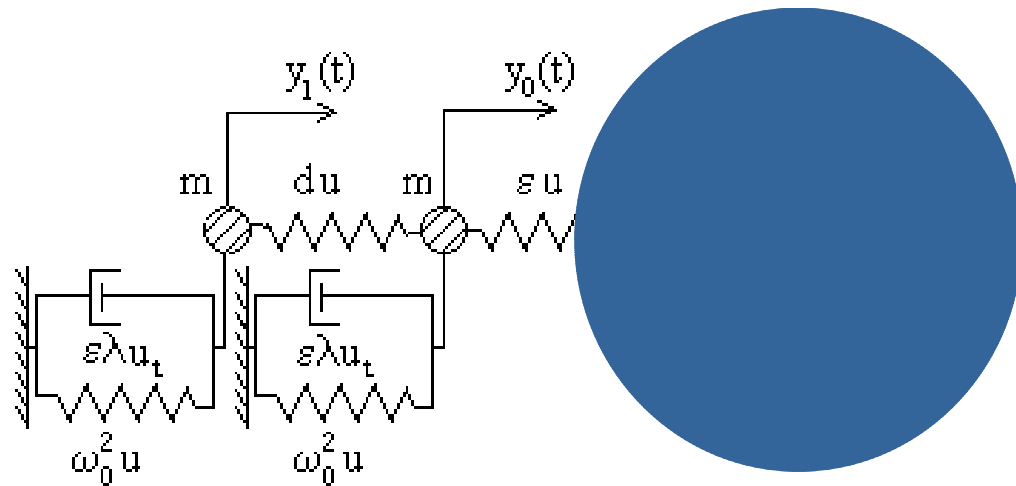
Variation with Level of Forcing

- The existence of a threshold input energy to produce pumping is demonstrated by comparing the results of weak and strong forcing
- Stronger forcing does not always produce more efficient energy pumping



Experimental System: 2DOF + NES

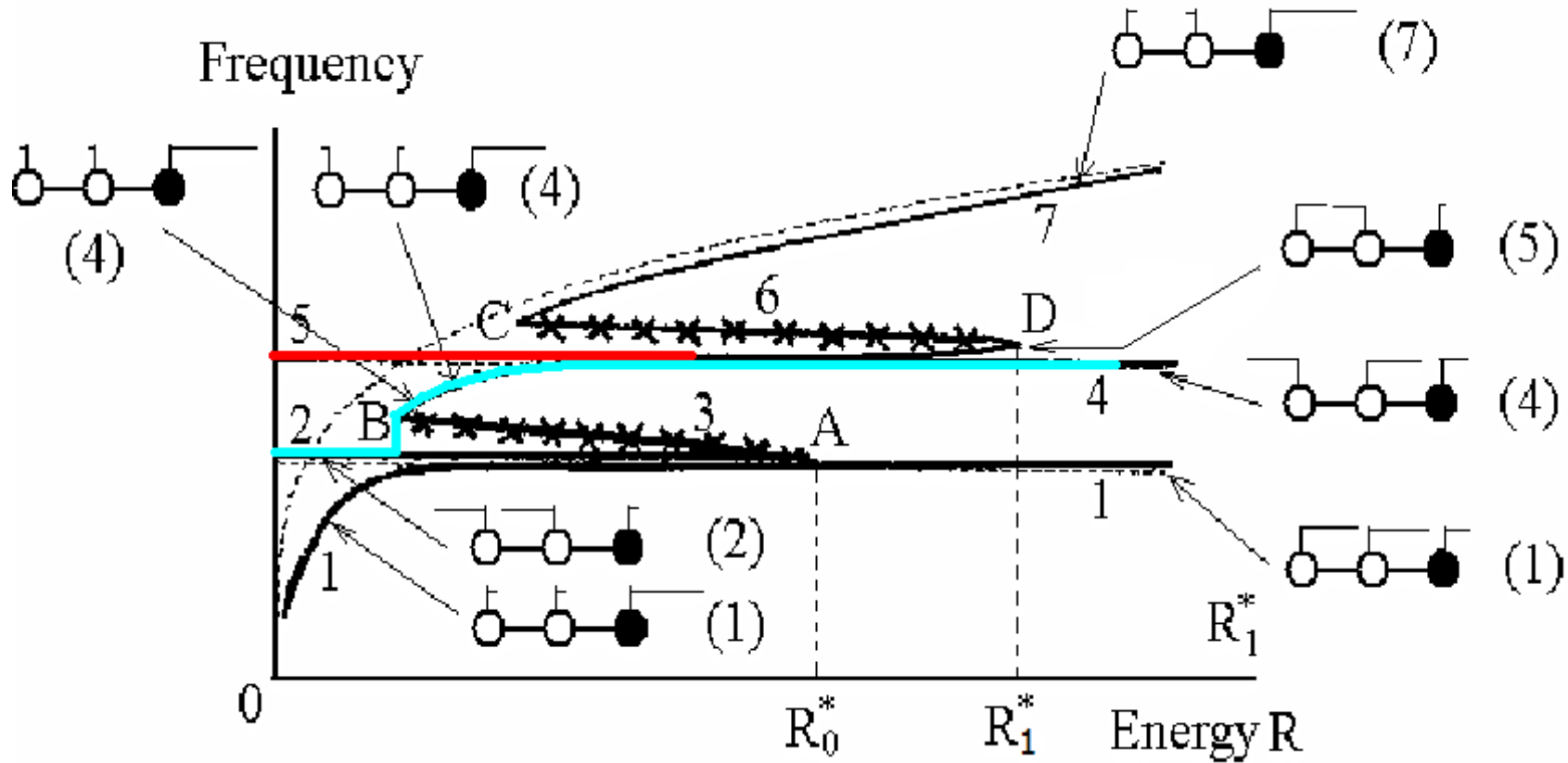
We next consider a 3-DOF system



Linear main system

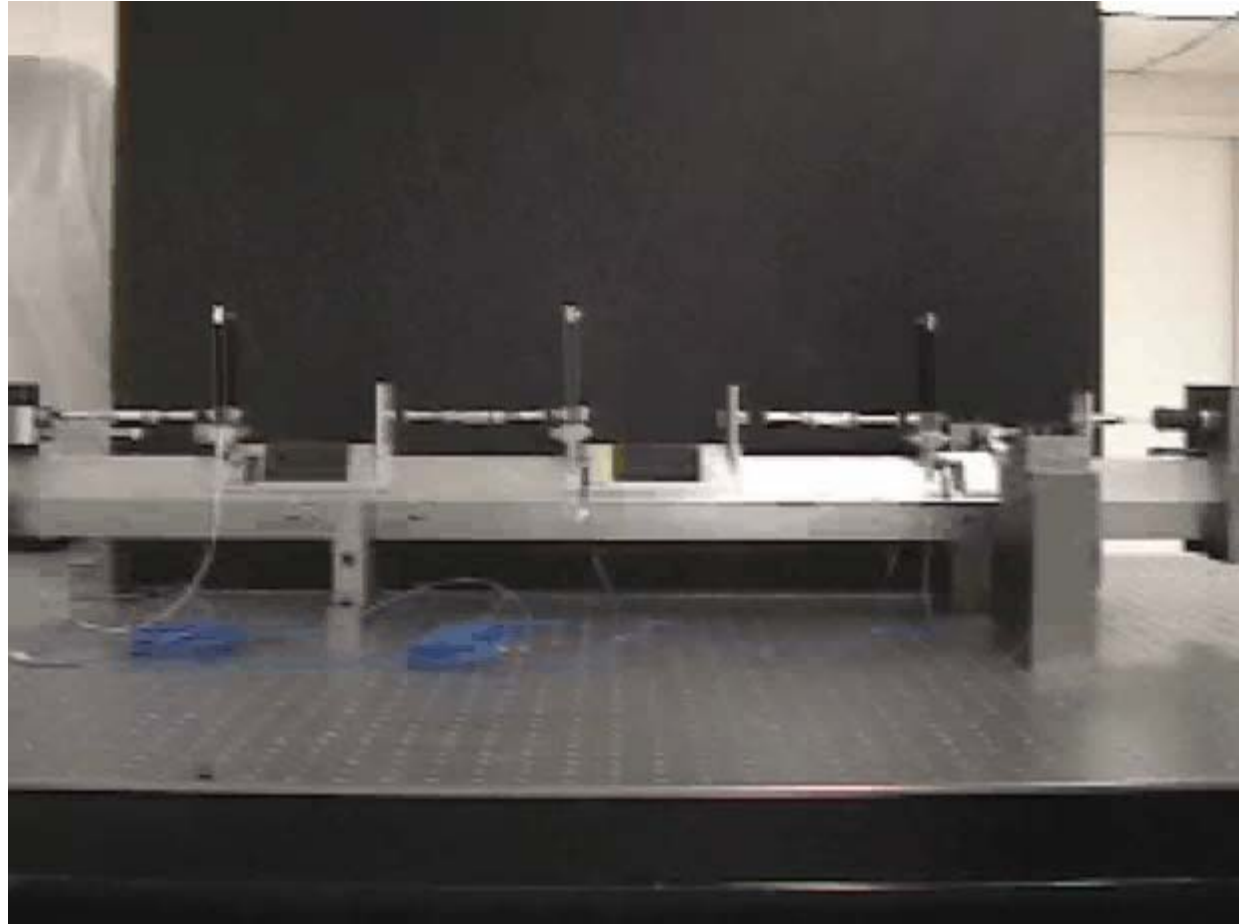
and seek to demonstrate transient resonance of the NES with both modes of the primary structure

Resonance Capture Cascade

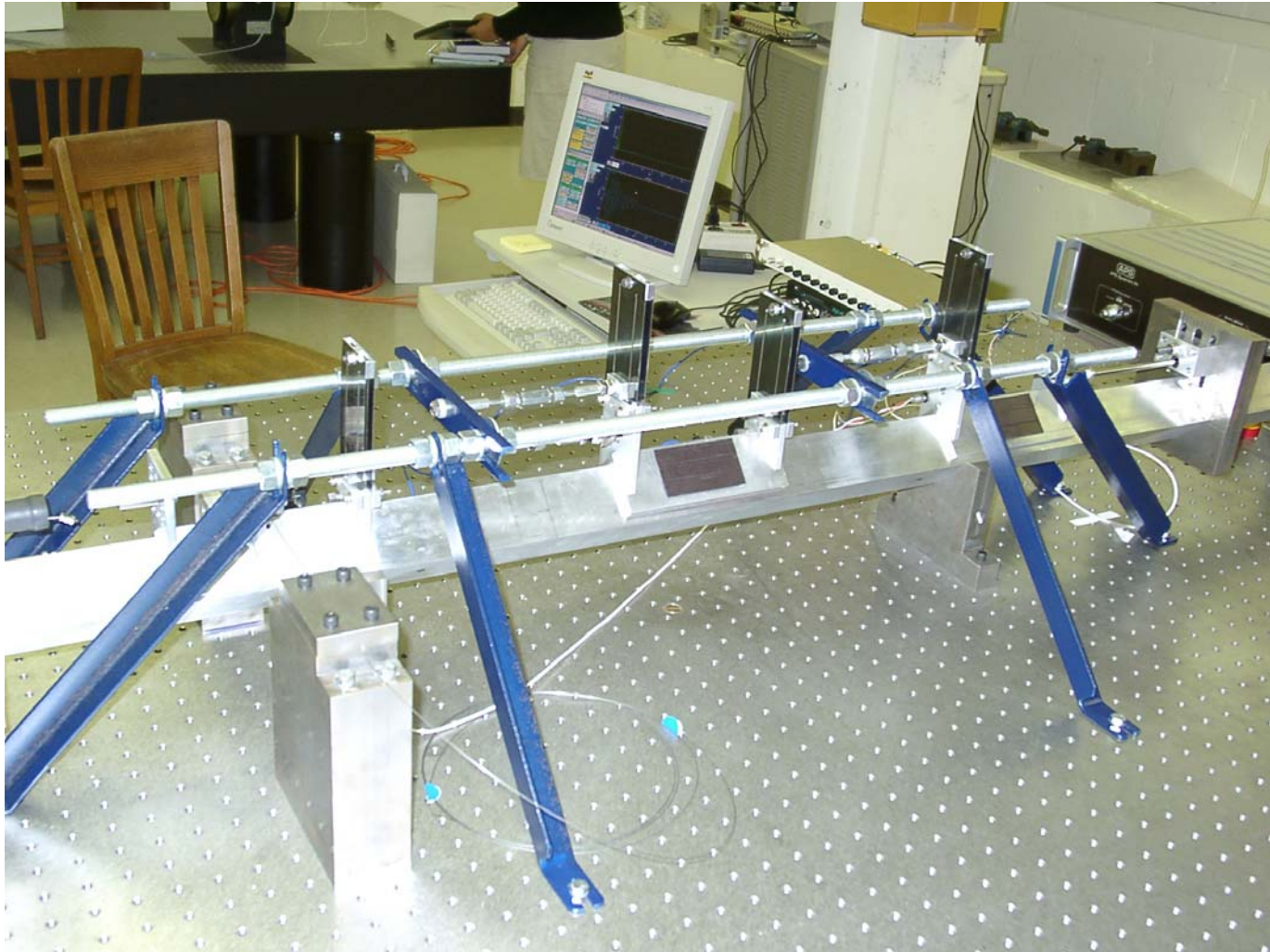


Experimental System: 2DOF + NES

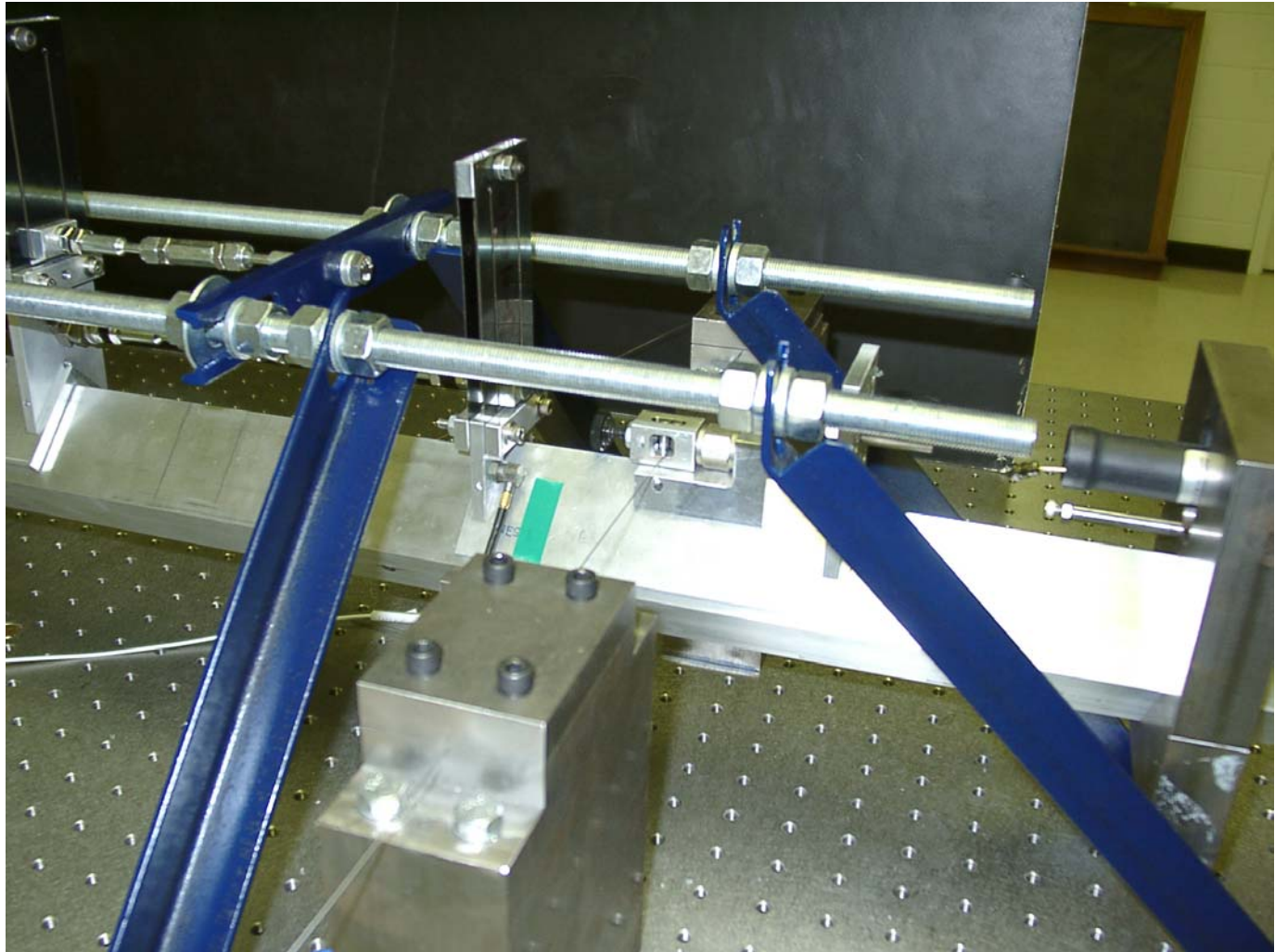
- Additional primary mass
- Same energy sink



Experimental System: 2DOF + NES

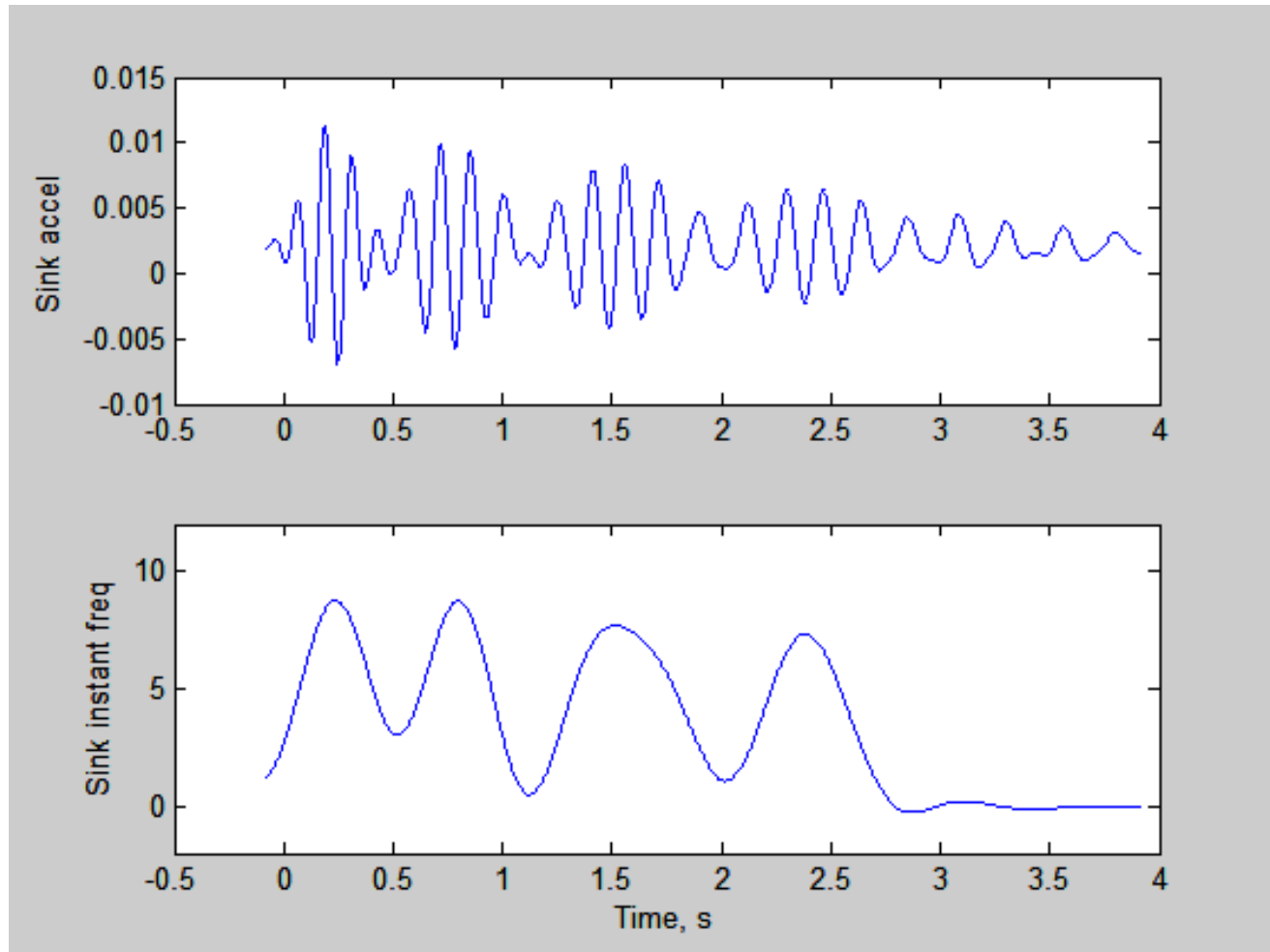


Experimental System: 2DOF + NES



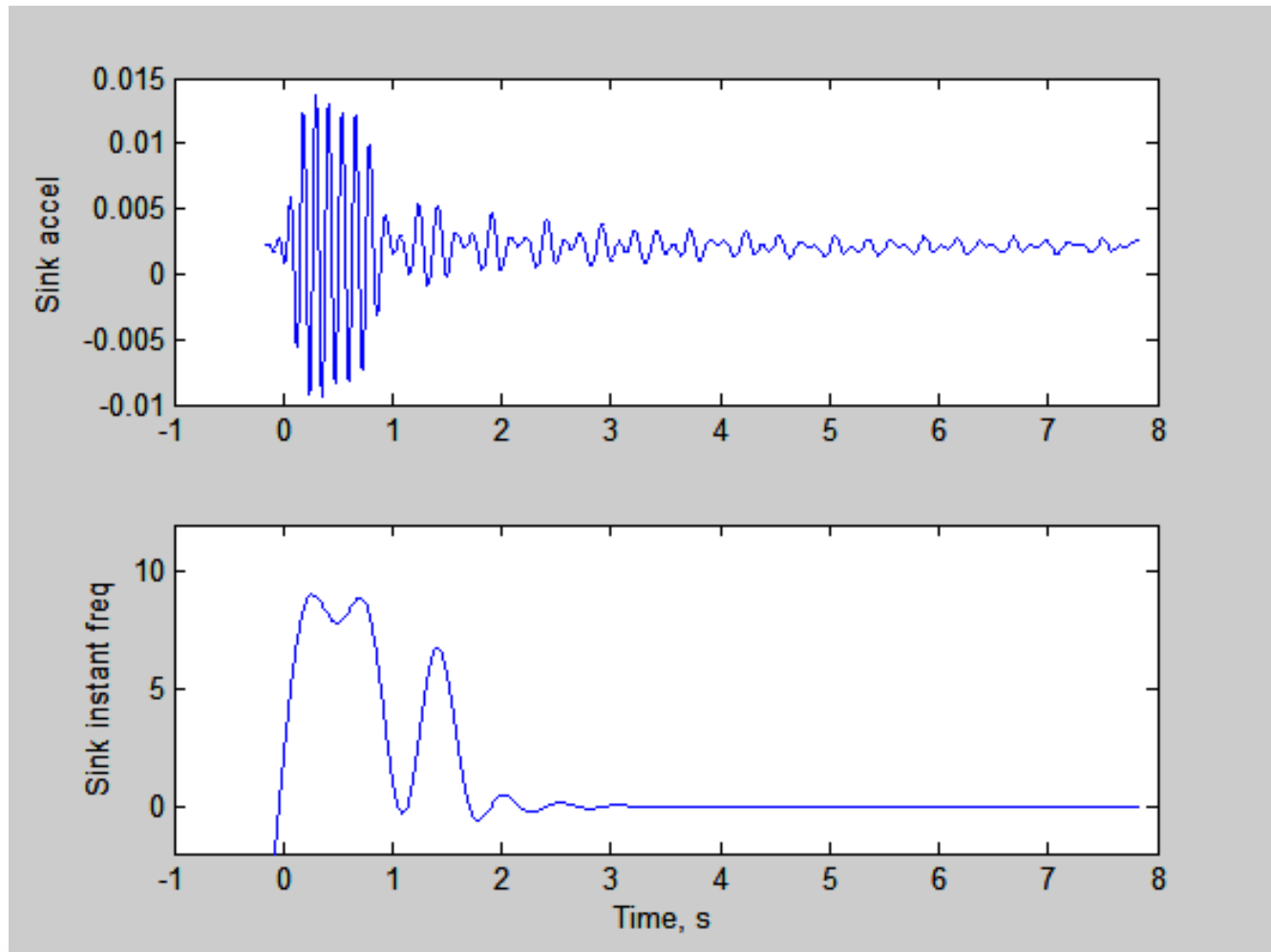
Measured Sink Response

- Pumping from mode 1 only



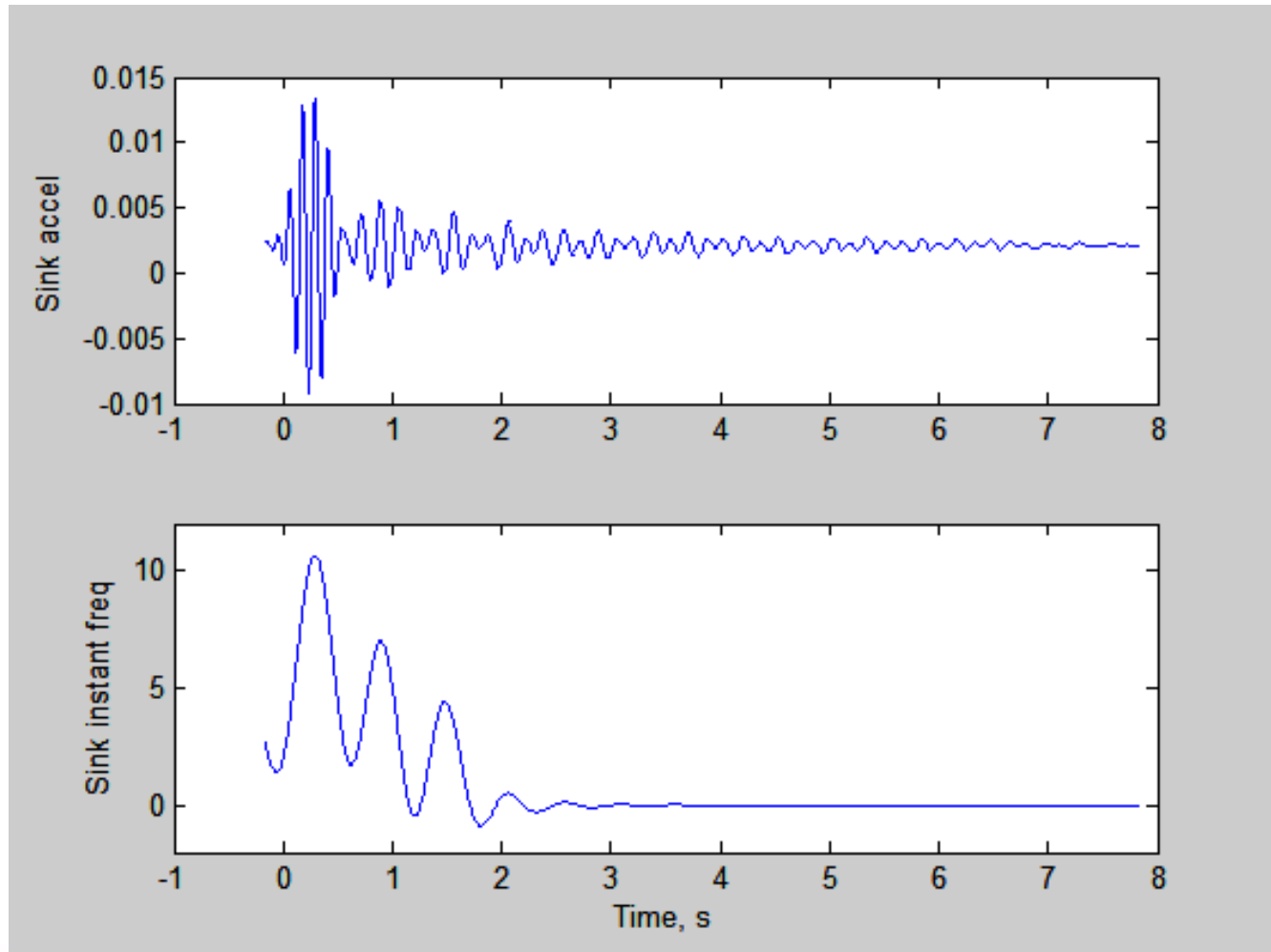
Measured Sink Response

- A brief cascade



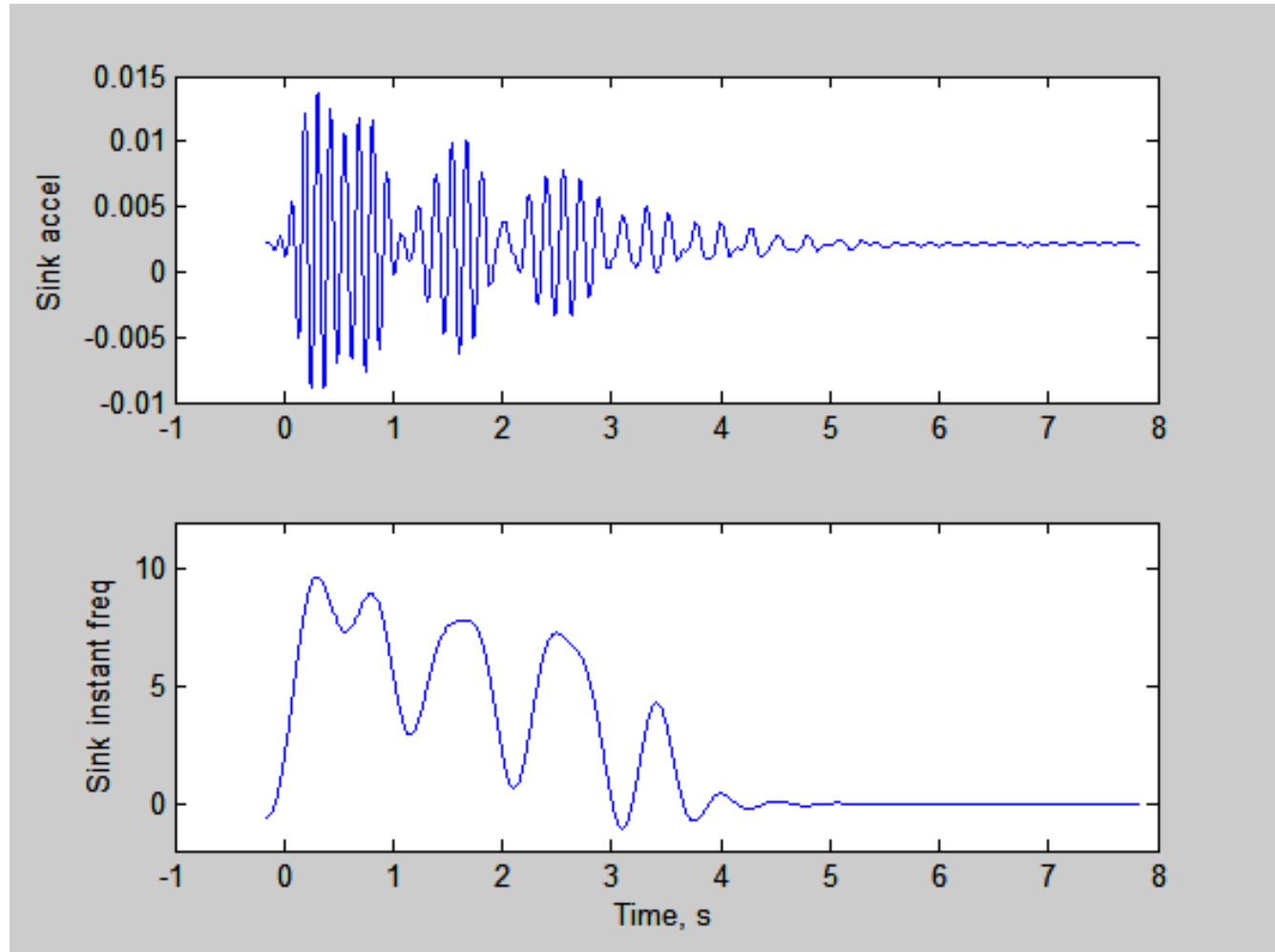
Measured Sink Response

- A sustained cascade (example 1)



Measured Sink Response

- A sustained cascade (example 2)



Conclusions

- Experimental results confirm the existence of nonlinear energy pumping, occurring at a single fast frequency approximately equal to the eigenfrequency of the linear subsystem
- Good agreement between theoretical and experimental results was observed in spite of the strongly nonlinear and transient nature of the dynamics
- Previous analytical and simulation results on the input energy threshold and the variation of efficiency with increasing forcing have been verified
- Evidence of energy pumping cascades from a 2-DOF primary system to a SDOF sink has been found