

# Characterisation and simulation of porous foams

## Some recent results



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OF TECHNOLOGY

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# Background

Most porous materials are non-isotropic in elasticity/viscoelasticity/viscoacoustic properties

To derive adequate simulation models, these properties must be known with a relevant precision

Work has been on-going since the BRAIN project ended in the mid-90's.

Fibrous wools are modelled with a high degree of accuracy  
Open cell porous foams are still an open point

# Contents of lecture

Review results for fibrous wools

Review our early work on porous foams

Recent results (experimental/numerical) on foams

# Constitutive modelling

$$\boldsymbol{\sigma}_f = \hat{\mathbf{H}} \boldsymbol{\varepsilon}_f$$

$$\boldsymbol{\sigma}_f^T = [\sigma_{11} \quad \sigma_{22} \quad \sigma_{33} \quad \sigma_{12} \quad \sigma_{13} \quad \sigma_{23}]$$

$$\hat{\mathbf{H}} = \mathbf{H} + d_\lambda(s) \mathbf{H}_\lambda + d_G(s) \mathbf{H}_G$$

$$\mathbf{H}^{-1} = \begin{bmatrix} a & d & g & 0 & 0 & 0 \\ & a & g & 0 & 0 & 0 \\ & & b & 0 & 0 & 0 \\ & & & s & 0 & 0 \\ & & & & t & 0 \\ & & & & & t \end{bmatrix}$$

$$a = \frac{1}{E_1}; b = \frac{1}{E_2}; d = \frac{-\nu_1}{E_1}; g = \frac{-\nu_2}{E_2}; t = \frac{1}{G_2}; s = \frac{1}{G_1}$$

$$d_\lambda(s) = \sum_{l=1}^{N_a} \frac{(3\varphi_l^2 + 4\varphi_l\mu_l)}{\delta_l(s + \beta_l)} s$$

$$d_G(s) = \sum_{l=1}^{N_a} \frac{2\mu_l^2}{\delta_l(s + \beta_l)} s$$

$$s = \pm i\omega$$

$$\mathbf{H}_\lambda = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ & 1 & 1 & 0 & 0 & 0 \\ & & 1 & 0 & 0 & 0 \\ & & & 0 & 0 & 0 \\ & & & & 0 & 0 \\ & & & & & 0 \end{bmatrix}_{symm}$$

$$\mathbf{H}_G = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ & 2 & 0 & 0 & 0 & 0 \\ & & 2 & 0 & 0 & 0 \\ & & & 1 & 0 & 0 \\ & & & & 1 & 0 \\ & & & & & 1 \end{bmatrix}_{symm}$$

# Fibrous wools

Layered, within each layer randomly dispersed fibres

Elasticity assumed transversely isotropic

Poisson's ratios are ~zero, simplifying the process of finding the various moduli.

From static tests (example of fibrous wool used in aircraft):

Moduli	$E_1$	$E_2$	$G_1$	$G_2$
[Pa]	225	17200	1200	13700

# Fibrous wools, cont'd

Viscoelasticity assumed isotropic (!)

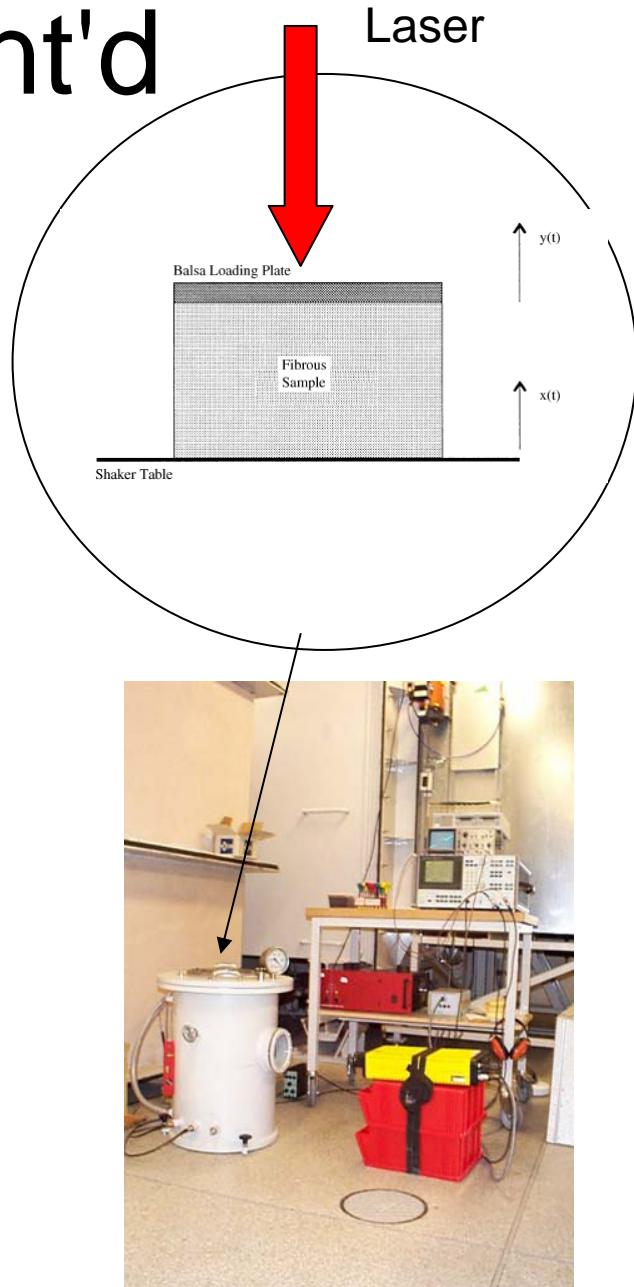
Uniform motion of the loading plate

From dynamic tests in vacuum chamber:

Moduli	$\beta_1$	$\mu_1$	$\delta_1$	$\varphi_1$
	6.65 Hz	15.4 Pa	1.0 Pa	0 Pa

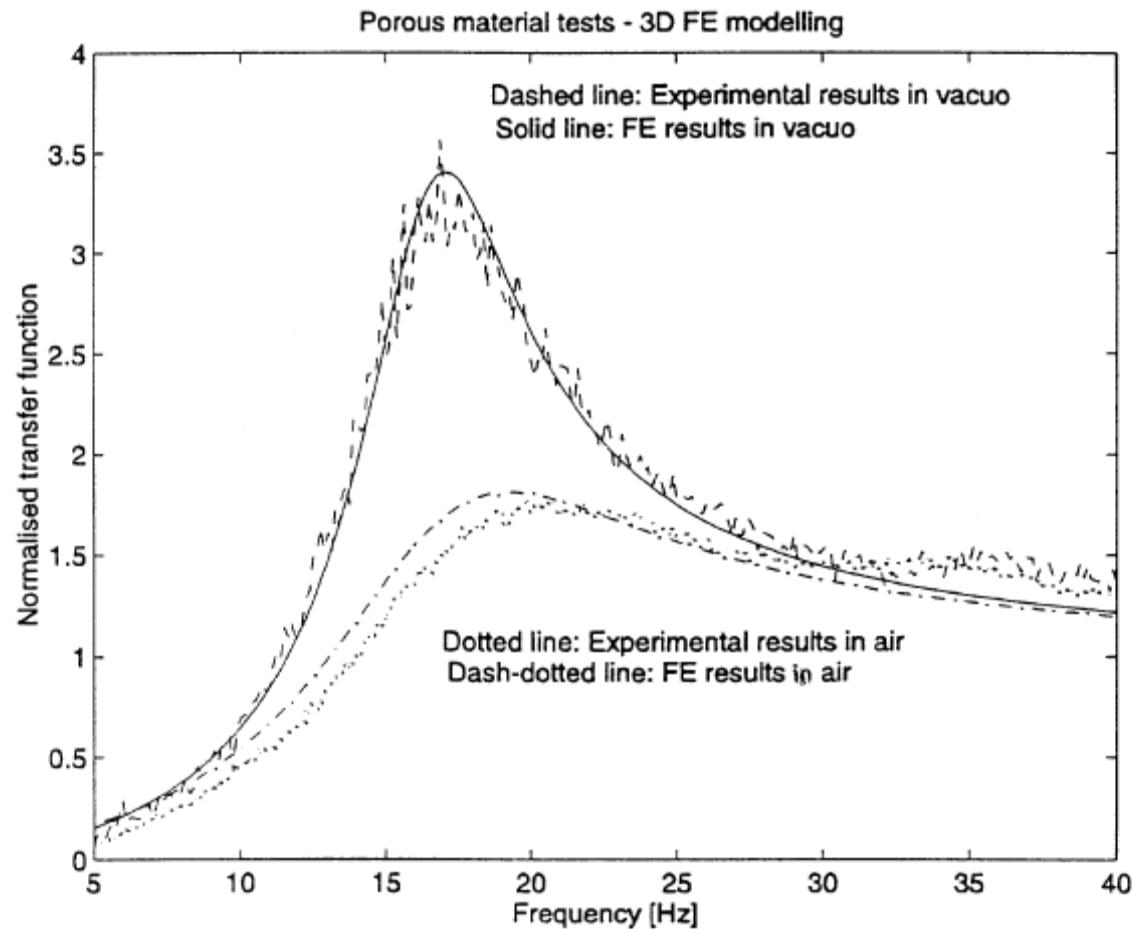
Note: Only one term needed + only in shear modulus

Equivalent loss factor ~10%



# Fibrous wools, cont'd

## Results



# Open cell foams (PU)

Foaming process induces a directional micro-structure

Properties vary throughout a real foam block

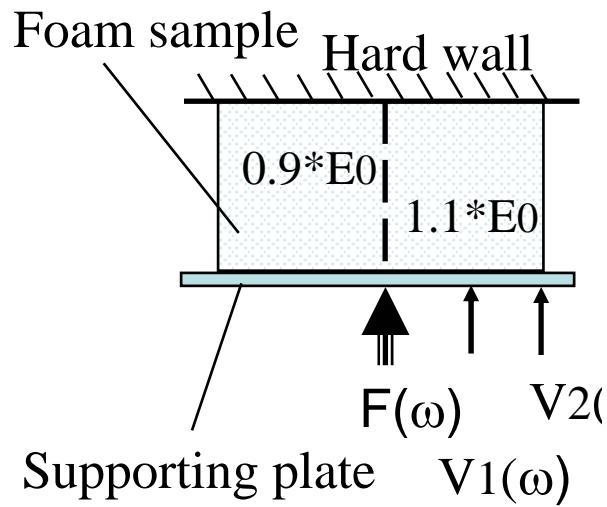
Degree and influence of non-isotropic elasticity?

"Naive" approach, use an isotropic elasticity model, but assume a variation in the in-plane direction.

$$E = 75 \text{ kPa}; \nu = 0.40$$

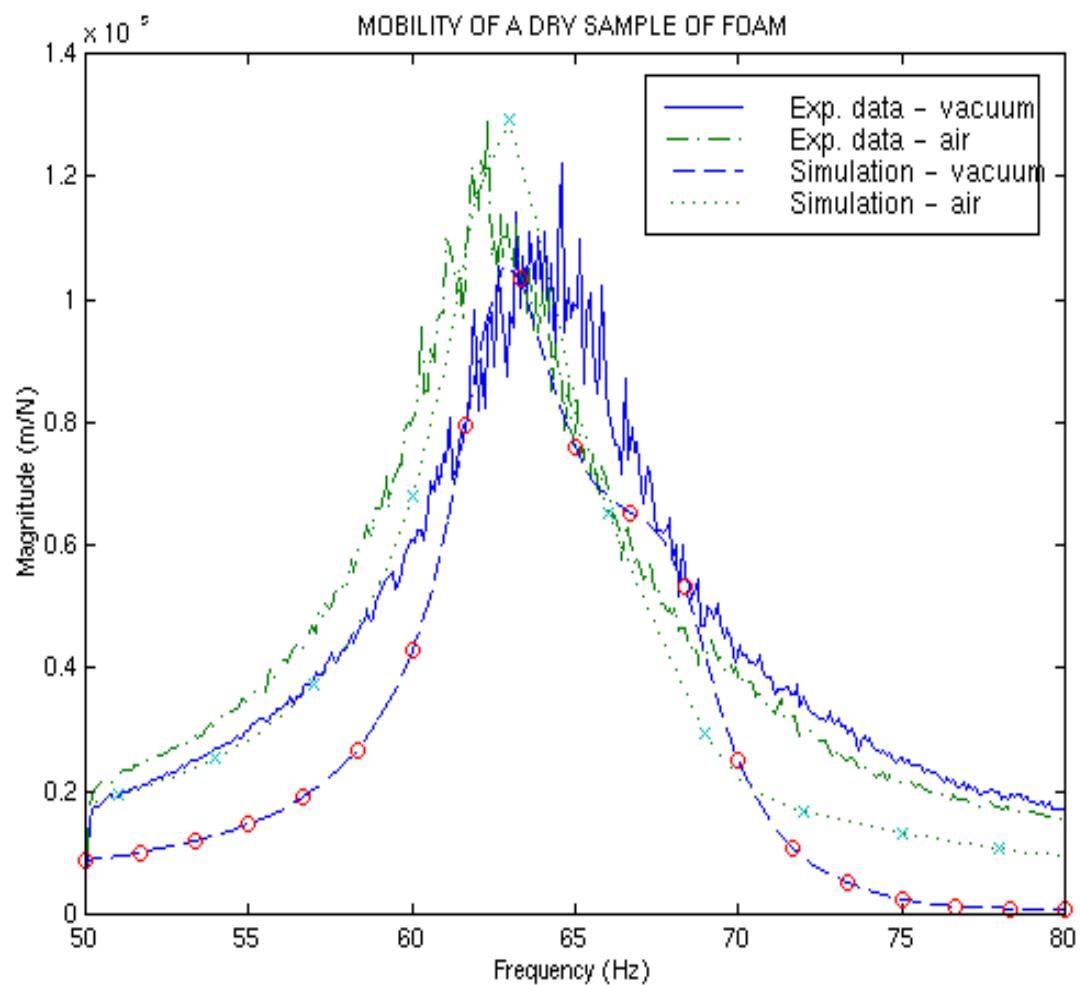
Moduli	$\beta_l$	$\mu_l$	$\delta_l$	$\varphi_l$
$l=1$	1. Hz	71.30 Pa	1.0 Pa	71.95 Pa
$l=2$	1.E4 Hz	396.7 Pa	1.0 Pa	0 Pa

# Open cell foams (PU), cont'd

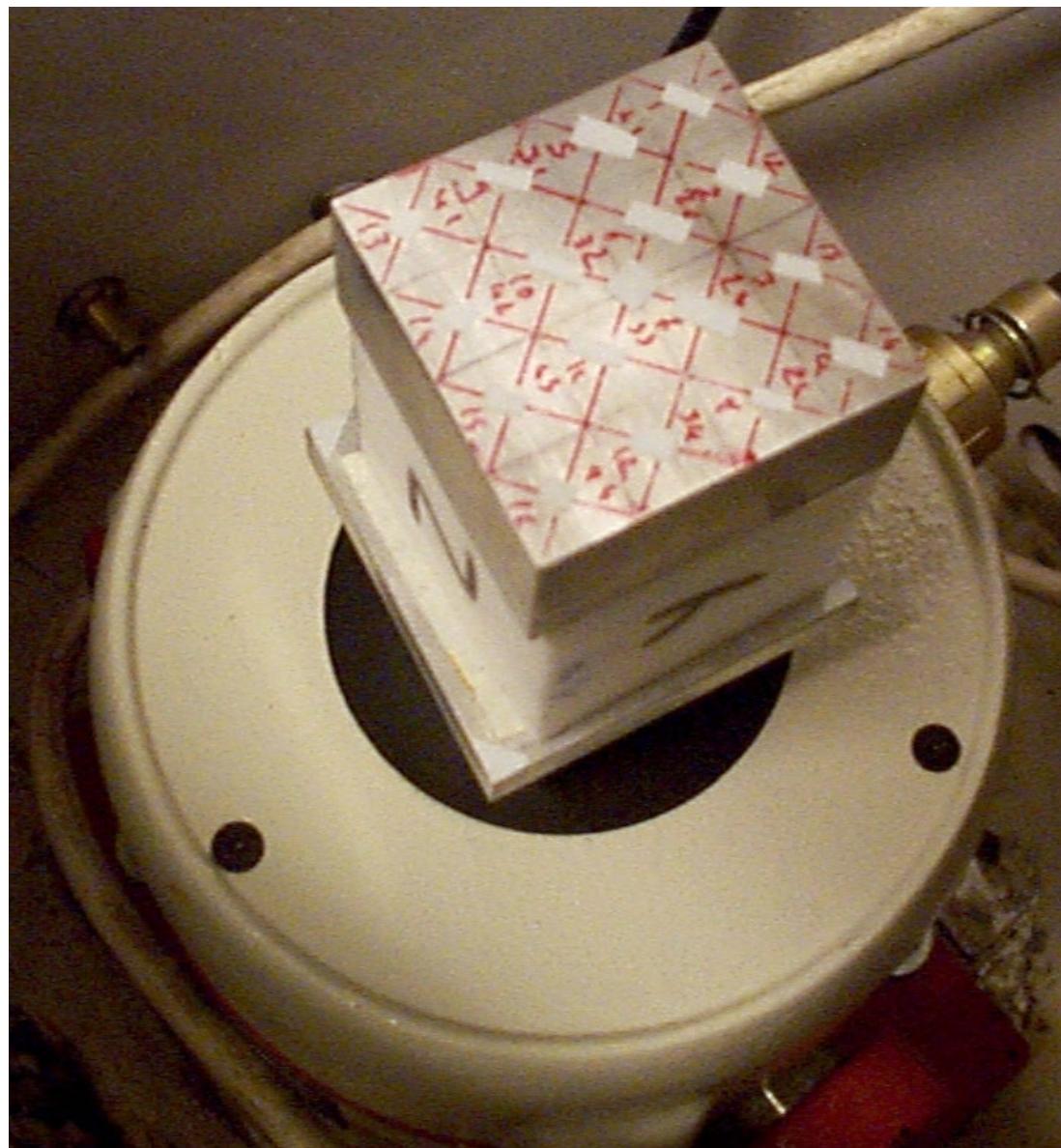
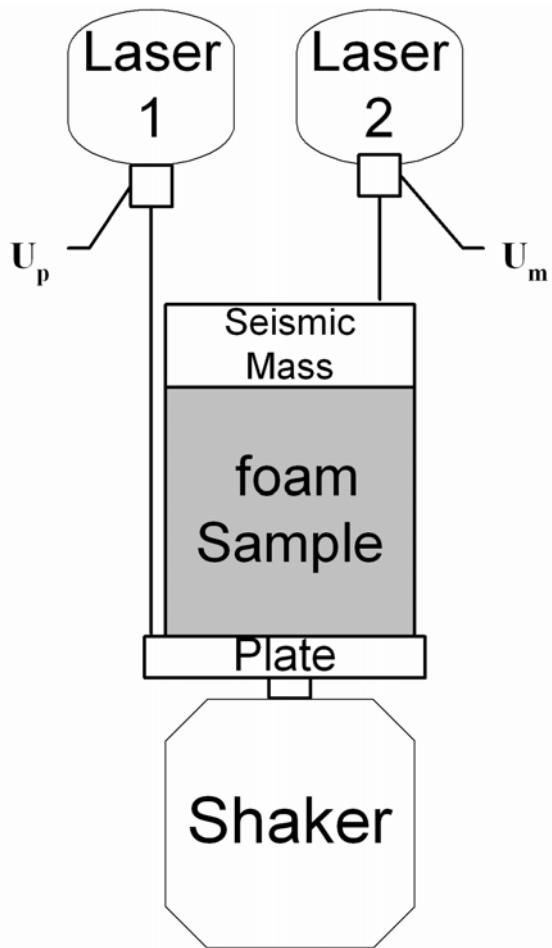


Supporting plate     $V_1(\omega)$

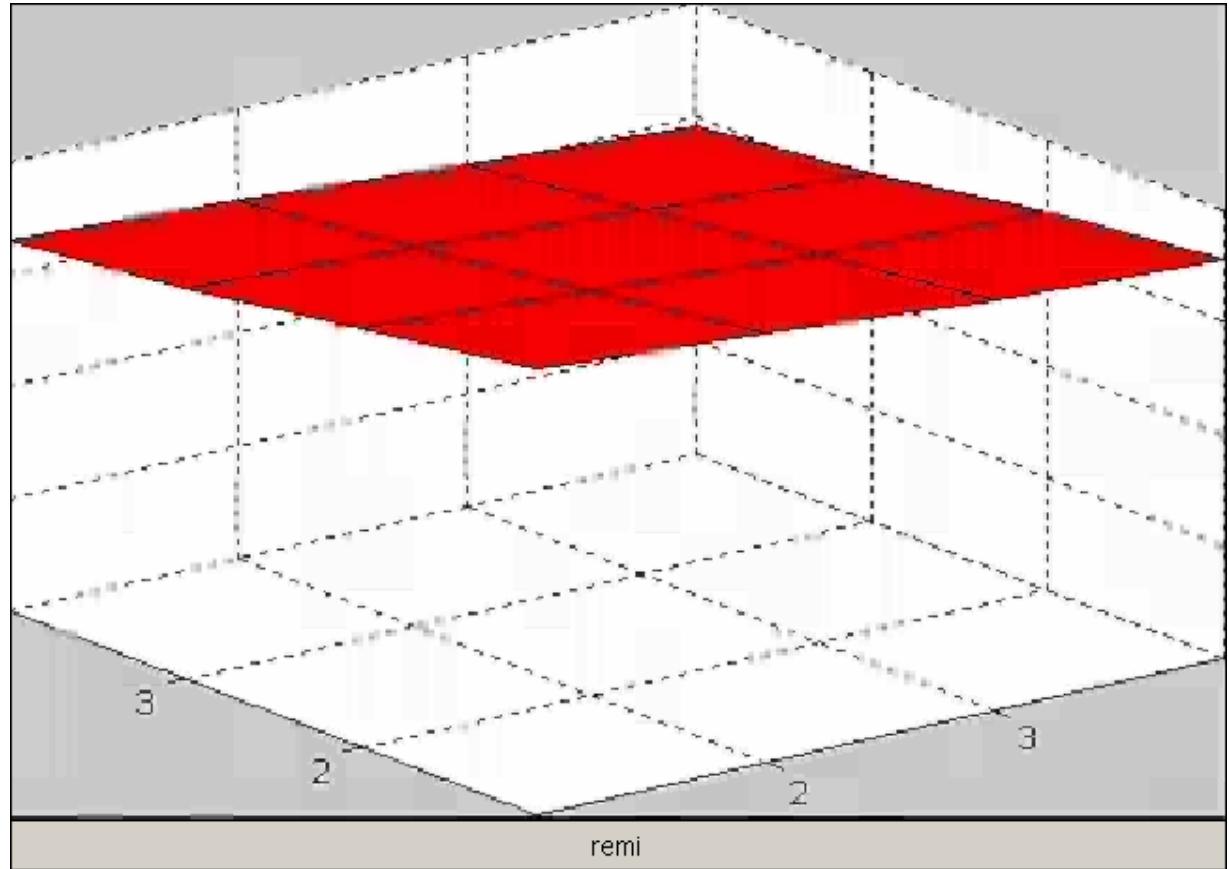
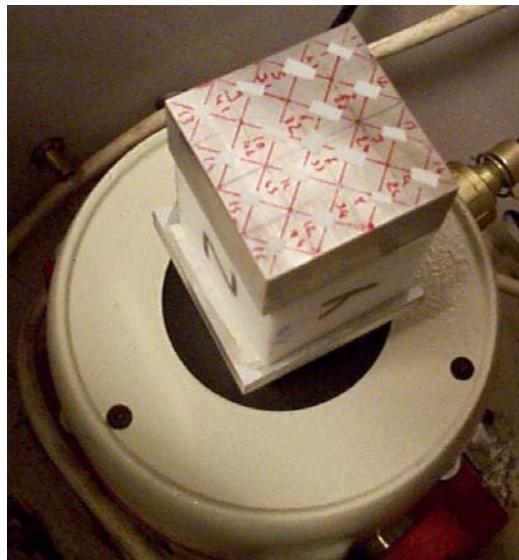
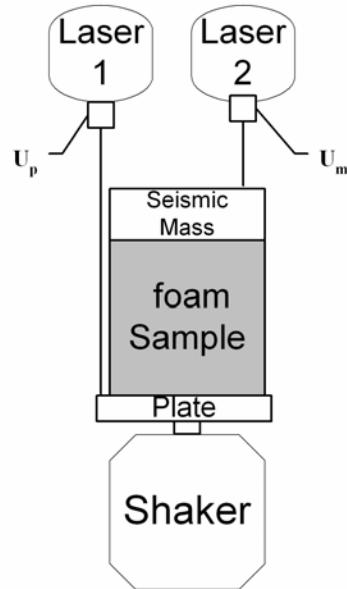
Non-uniform motion of  
supporting plate



# Dynamic experimental Setup

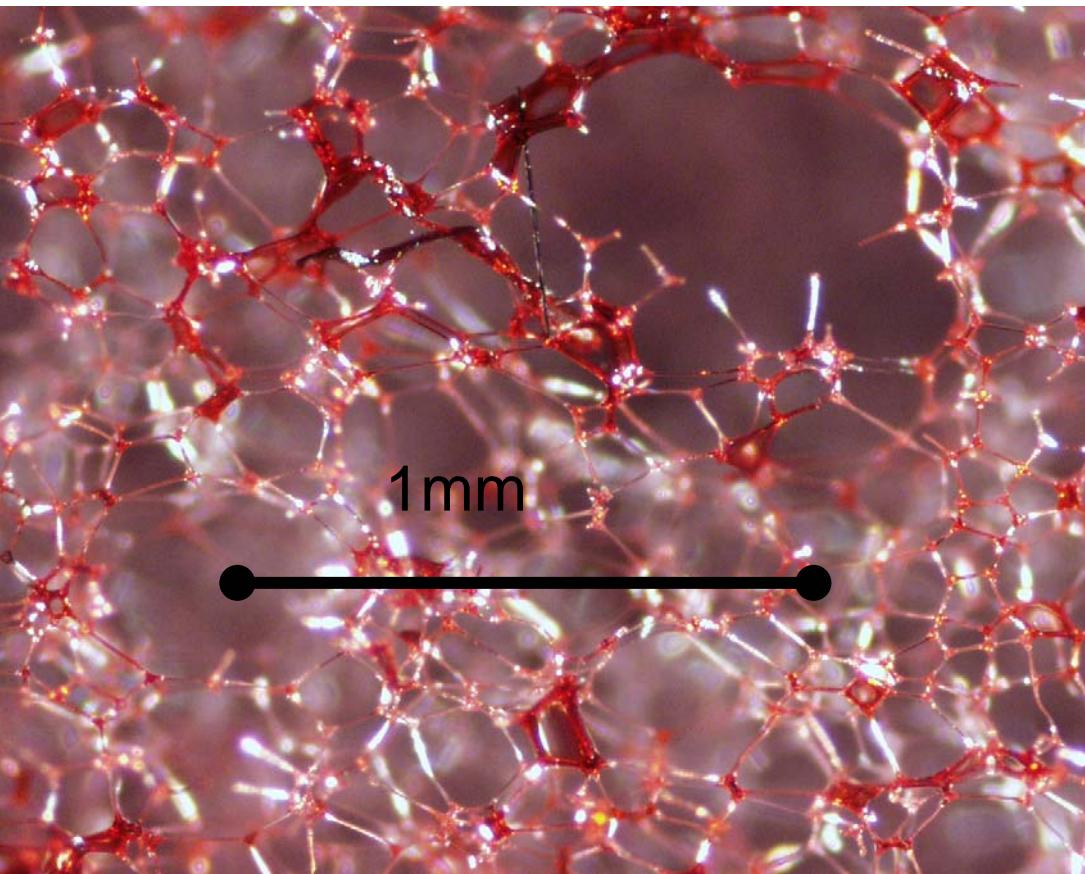


# Open cell foams (ME), cont'd

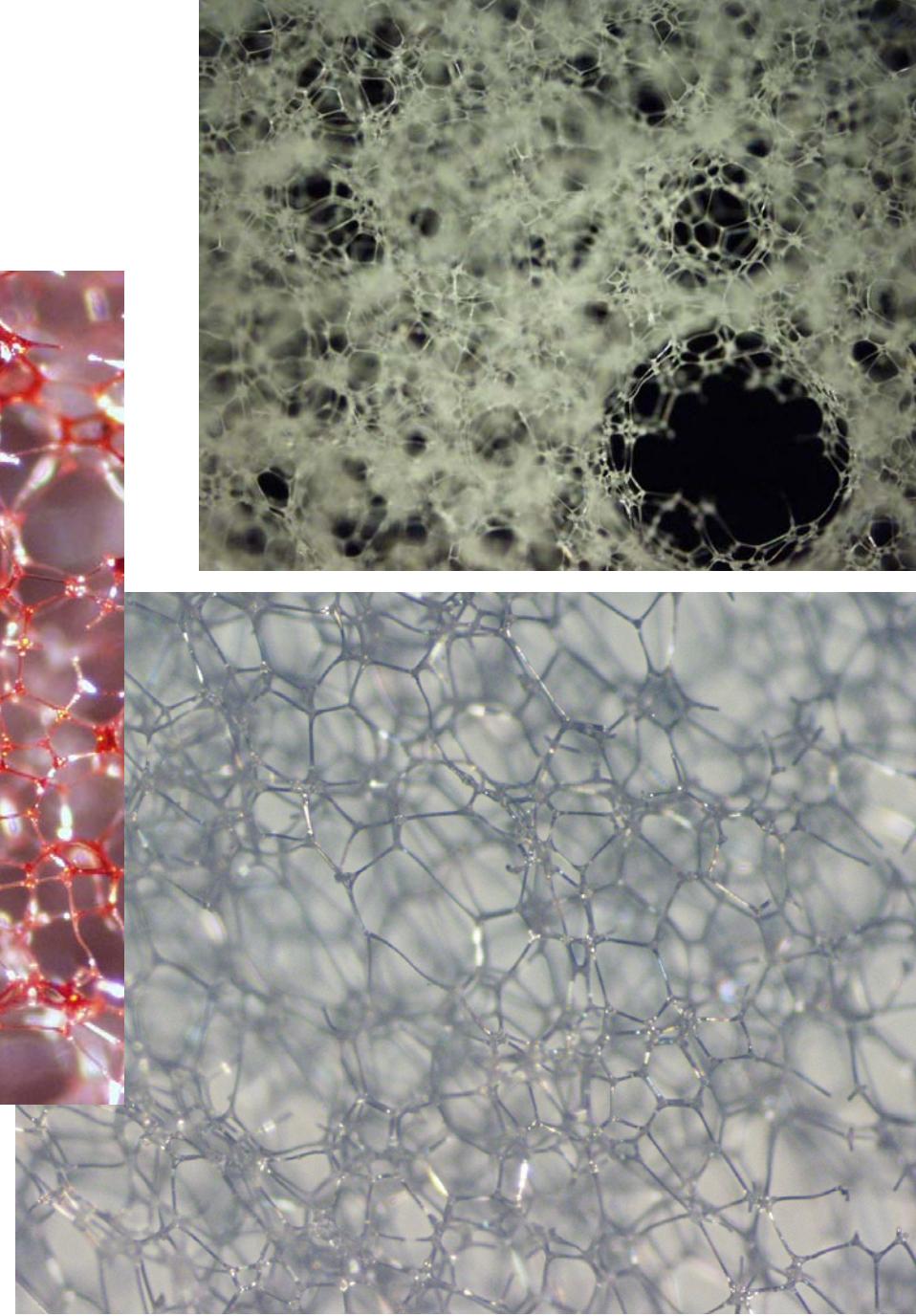


Non-uniform motion of  
supporting plate

# Microstructure Melamine



Cell orientation determines  
anisotropy



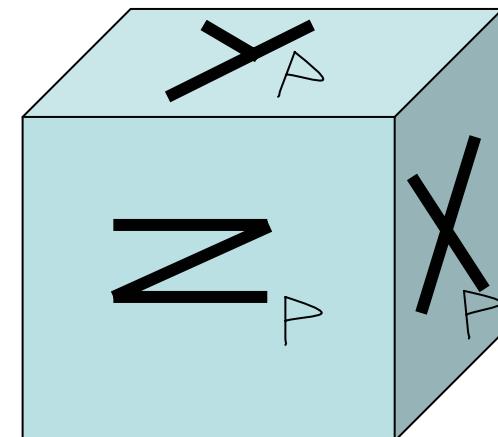
# Finding the elastic constants

Combined  
experimental/numerical

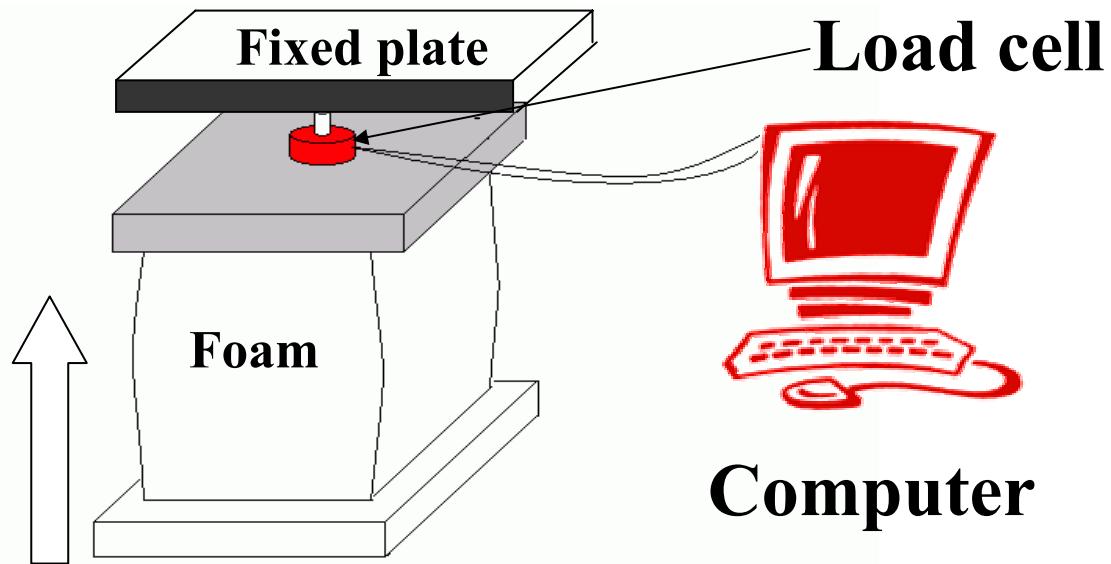
Inverse estimation through  
a least squares fit

First problem:

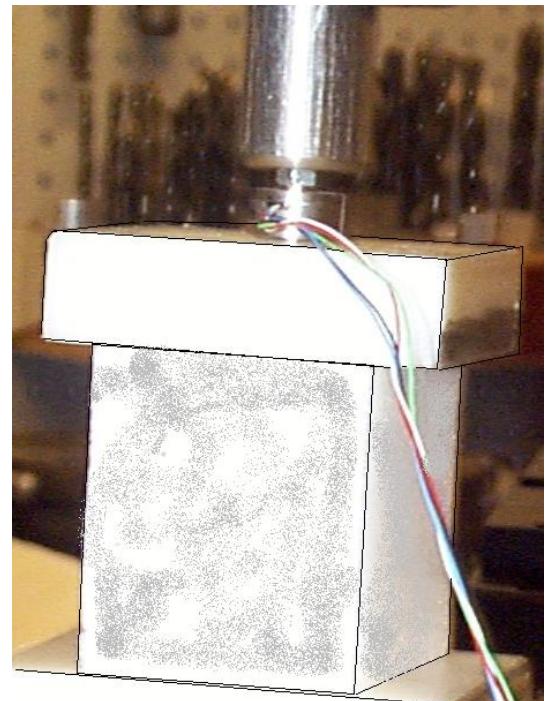
How to measure accurate  
deformations/forces?



# 1st static experimental setup /Load

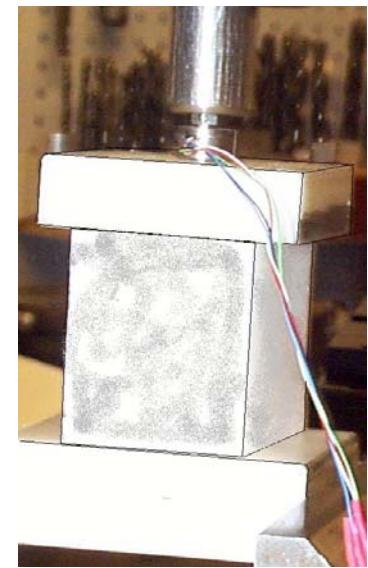
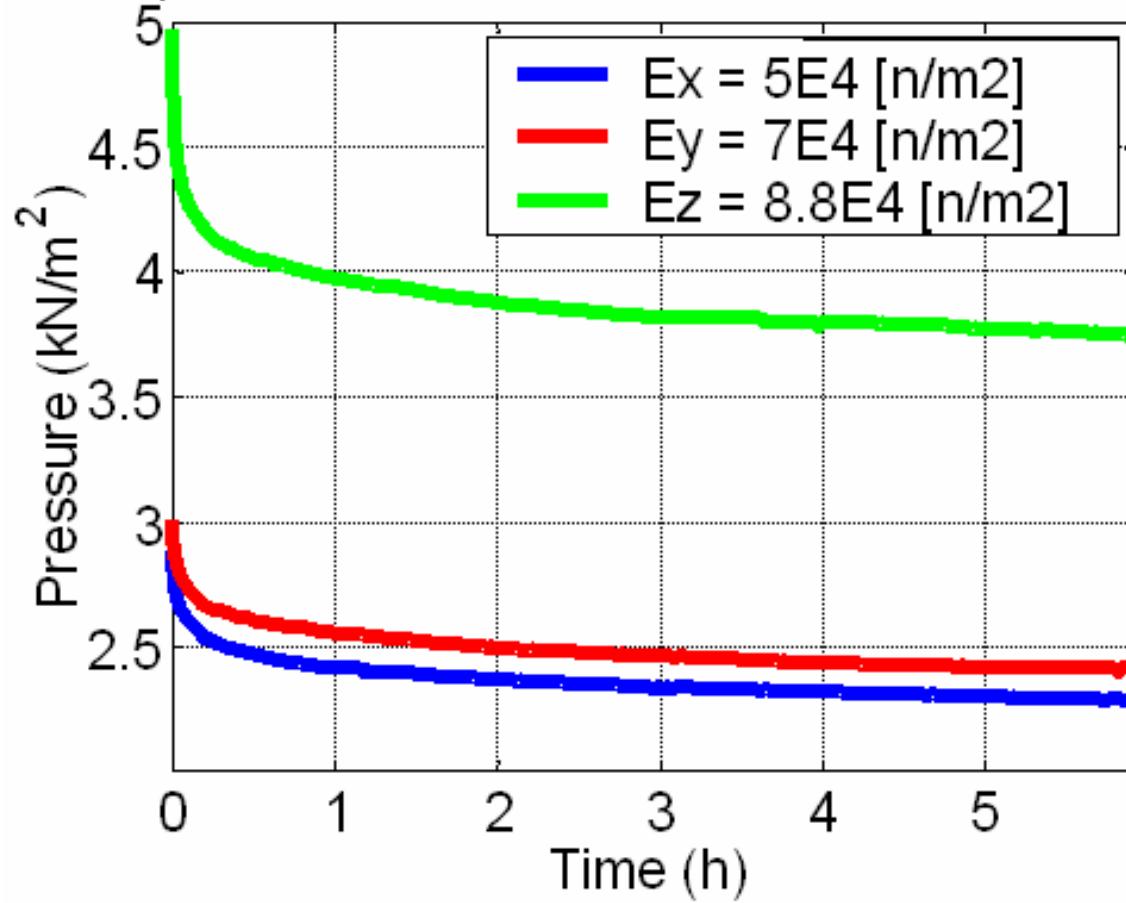


2,5%  
deformation



# Relaxation curve

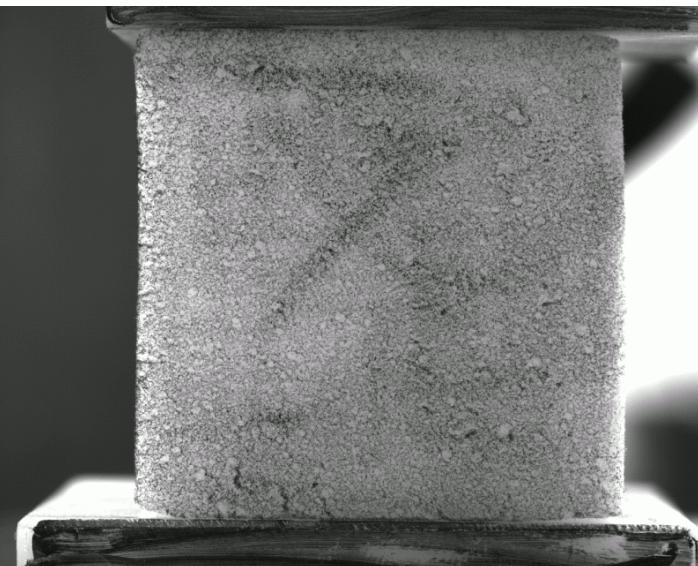
Experimental determination of the E modulus



Measuring small forces, weakness of load cell significant problem

# 2nd static test set-up

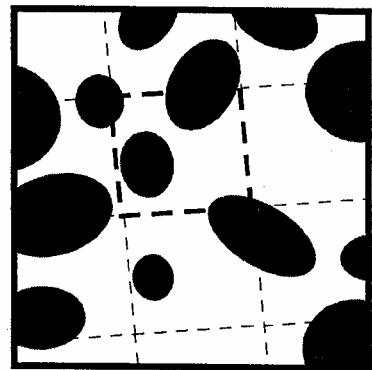
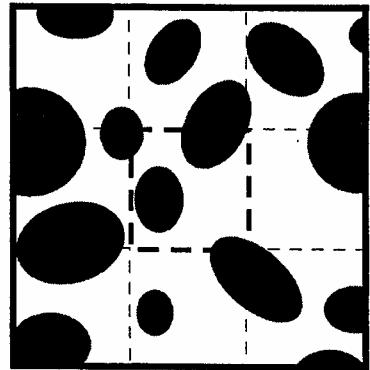
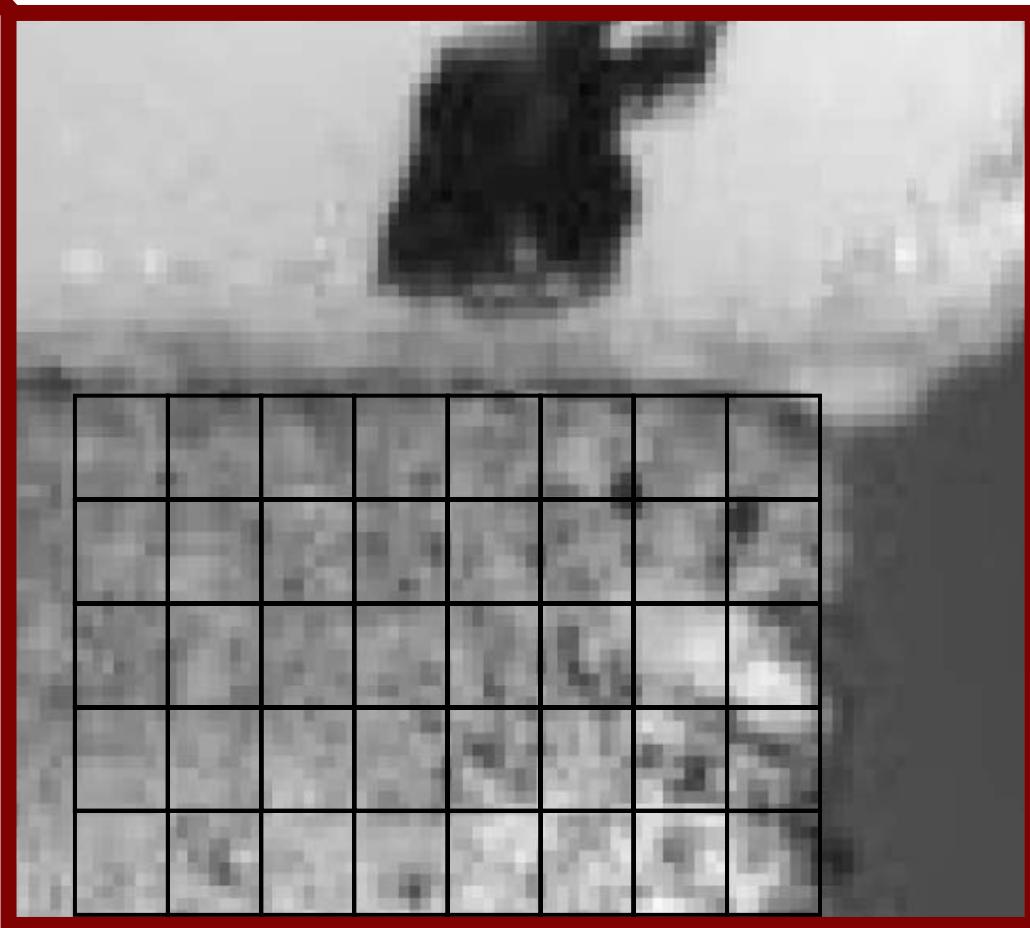
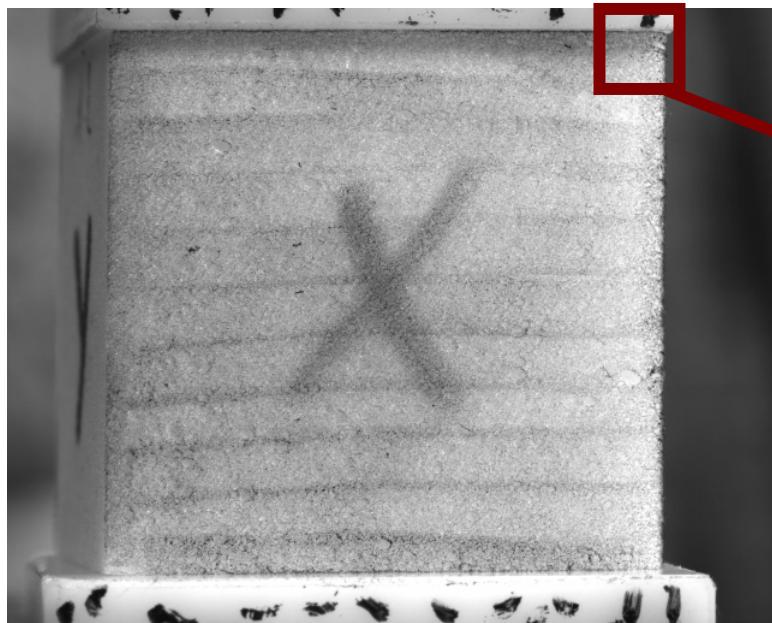
## CCD cameras and speckle photogrammetry



Used deformation  
level = 2.5 % strain  
to avoid nonlinearity



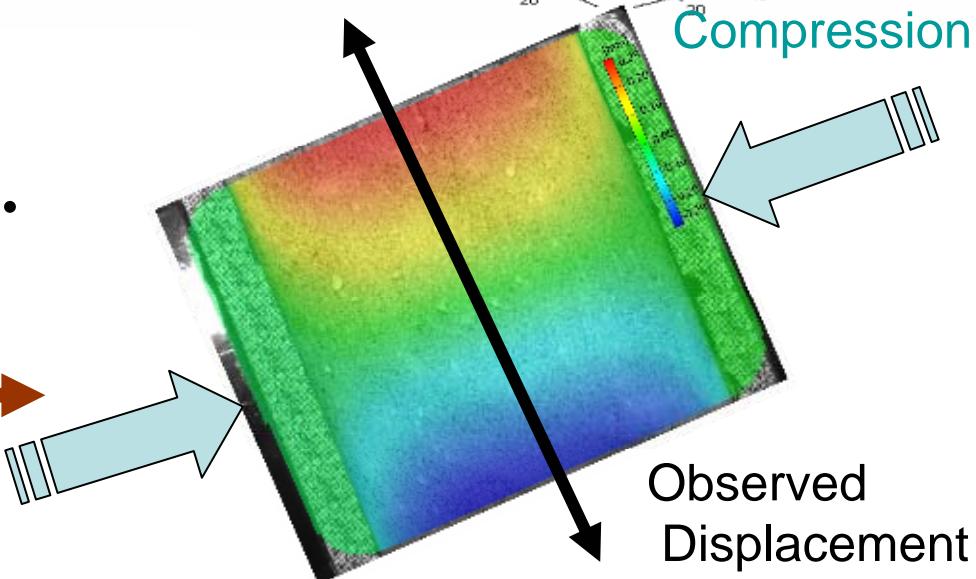
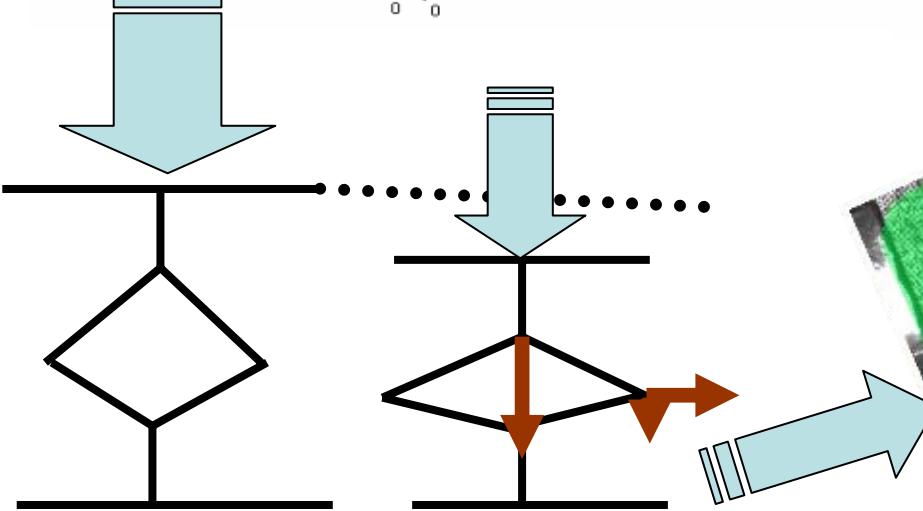
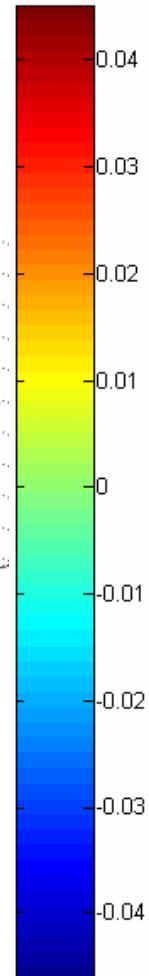
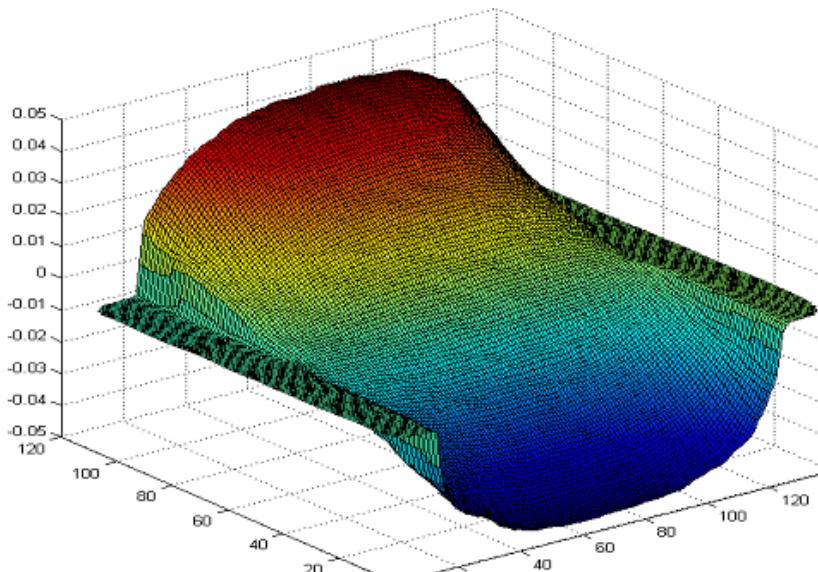
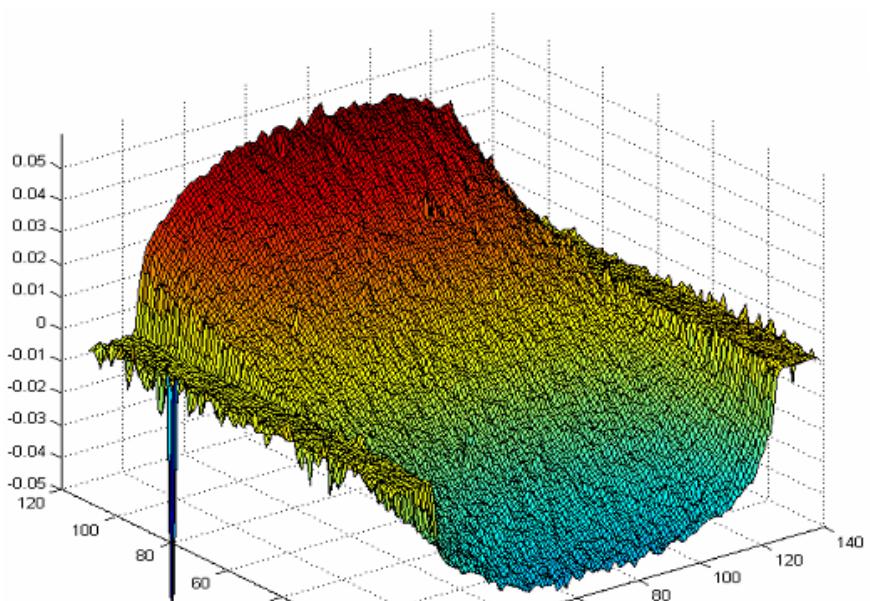
# CCD measurement



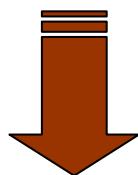
Before deformation

During deformation

# Typical result & smoothing



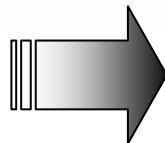
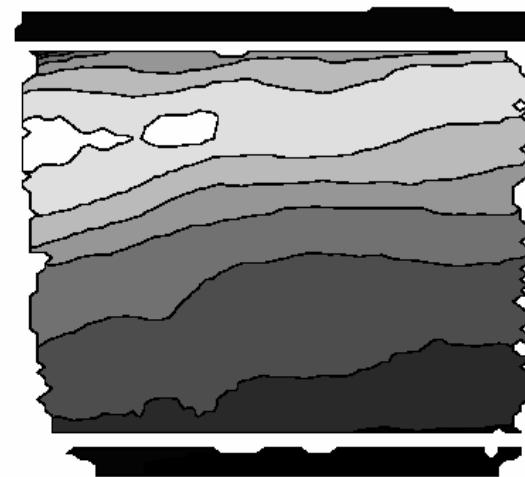
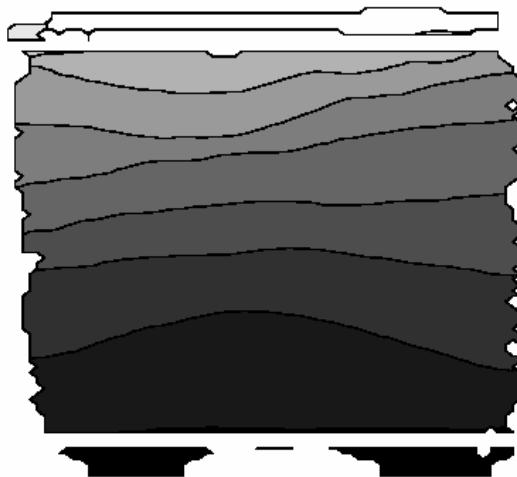
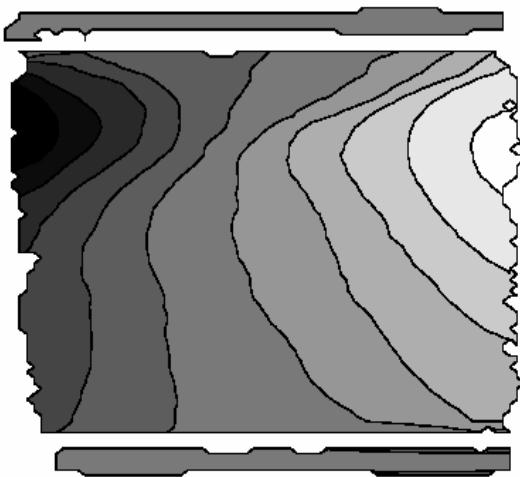
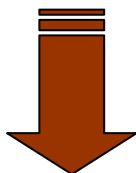
# Optical measurement result



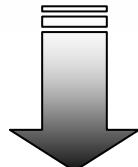
Compression



Compression



Deformation



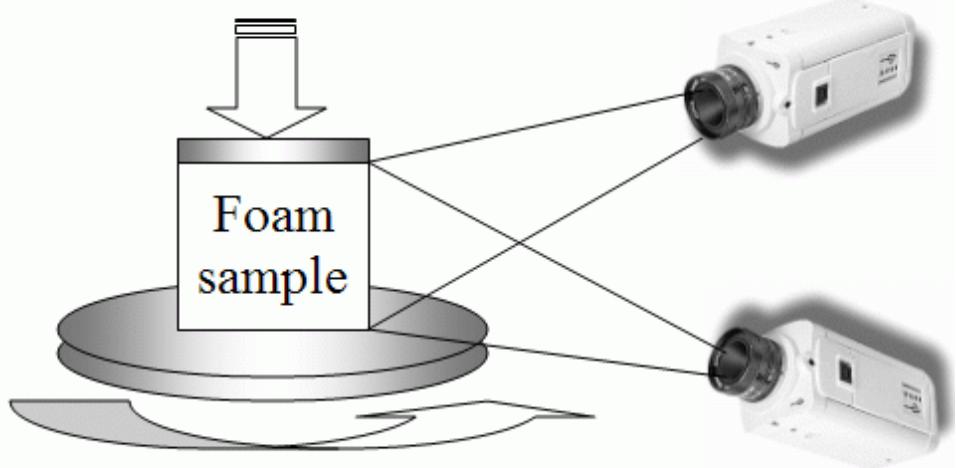
Deformation



# Rotating table



Constant deformation

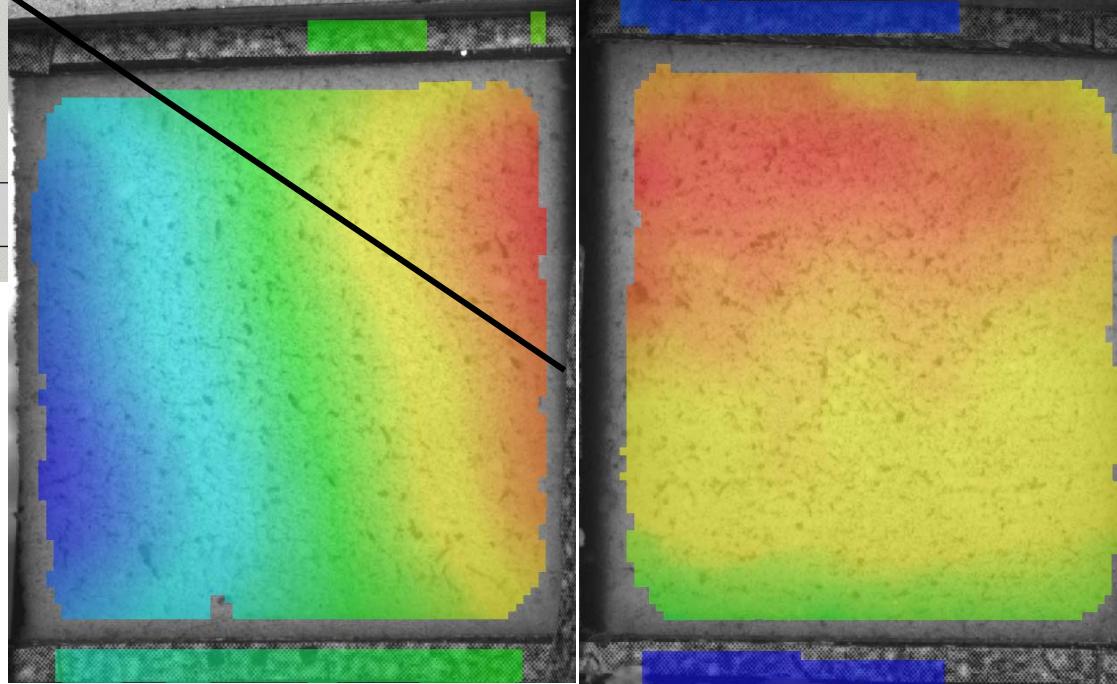
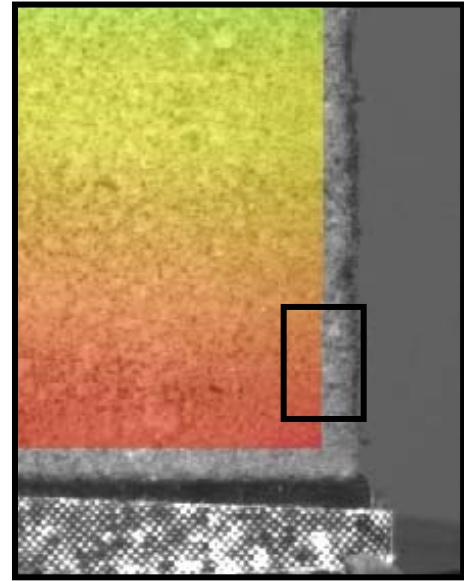
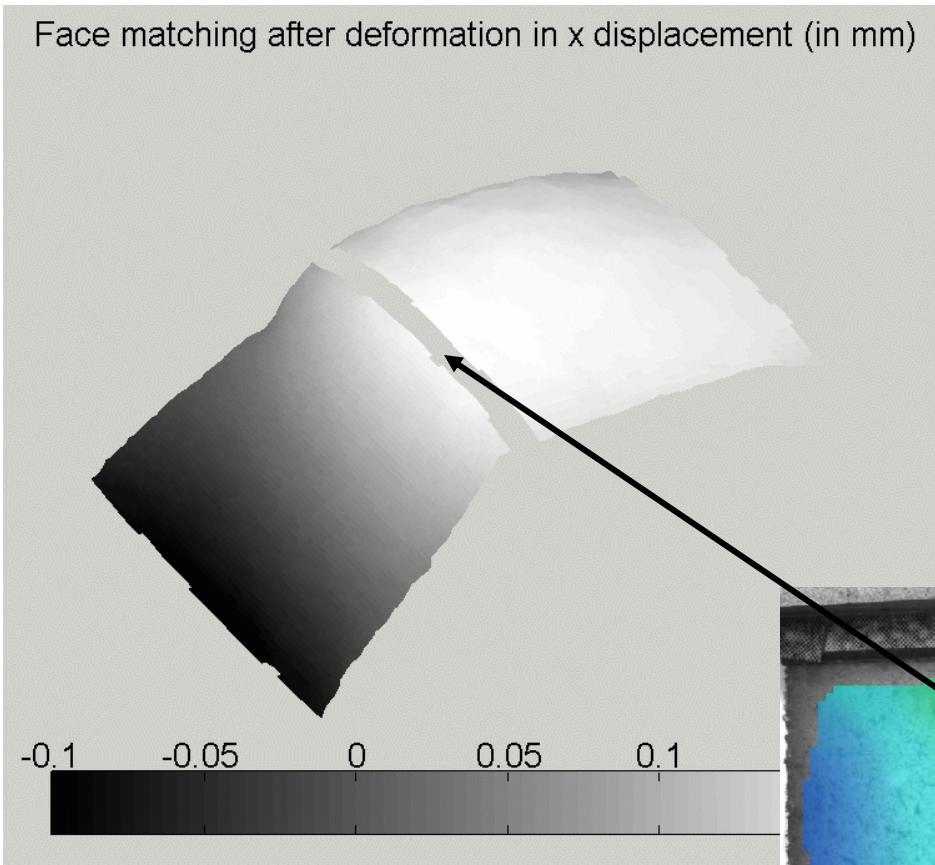


Rotating table

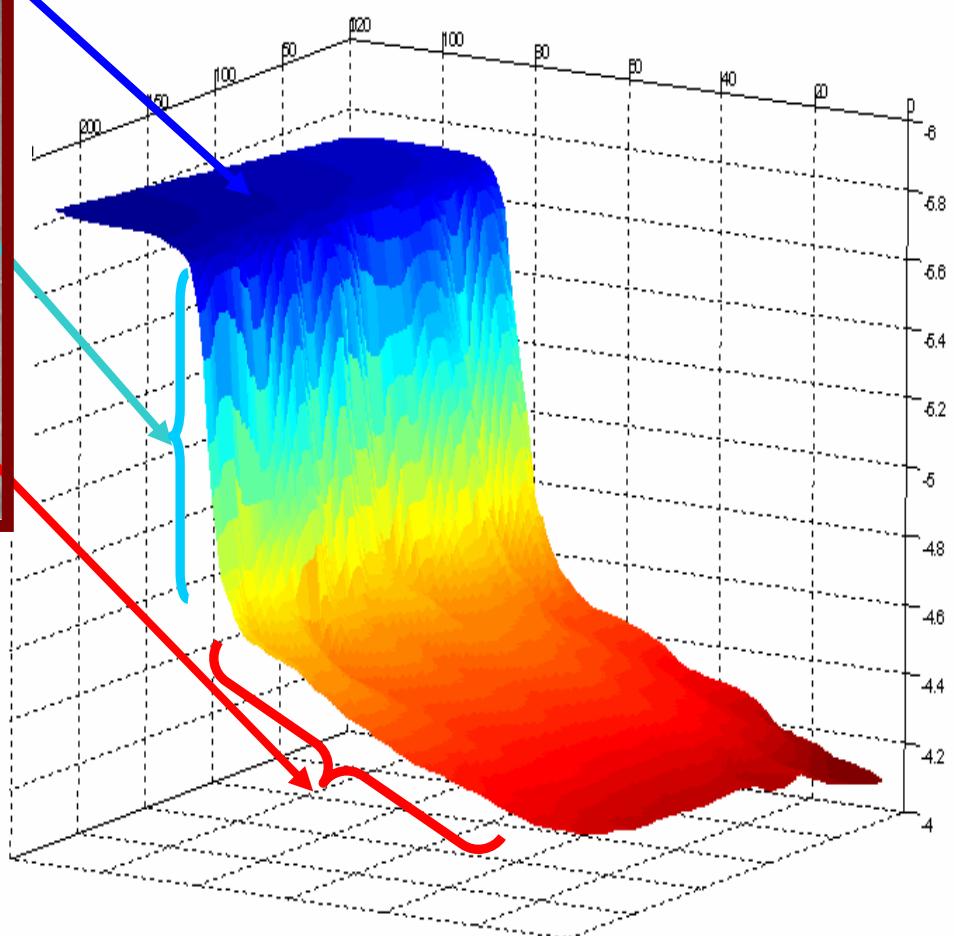
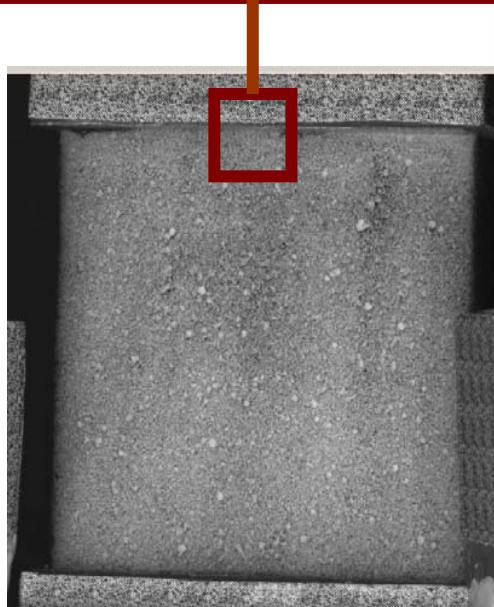
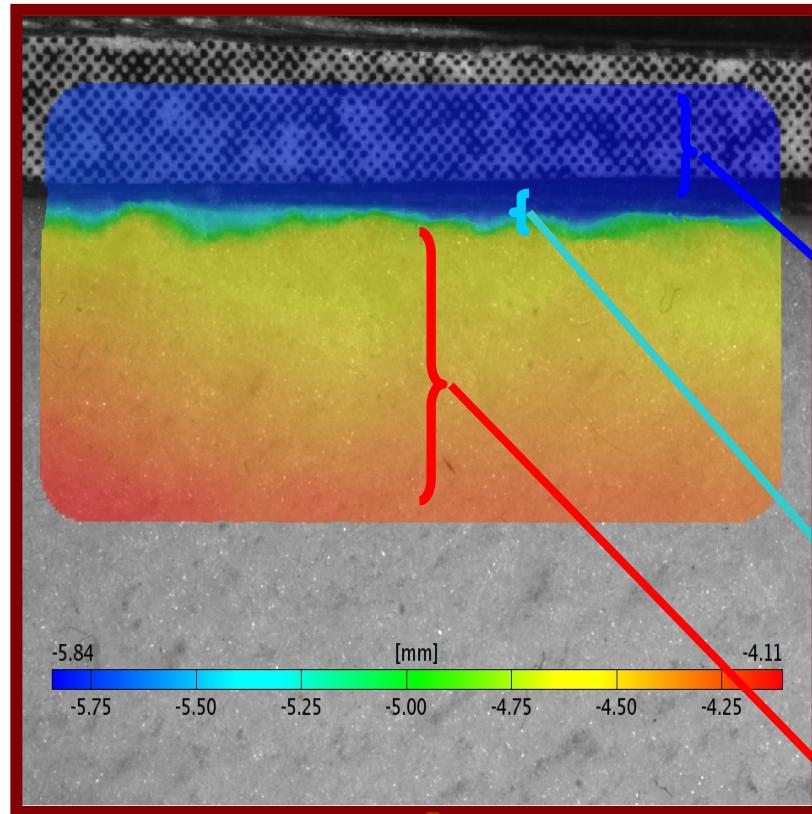
**Collect data for 4 faces  
without dismantling**

# Face matching

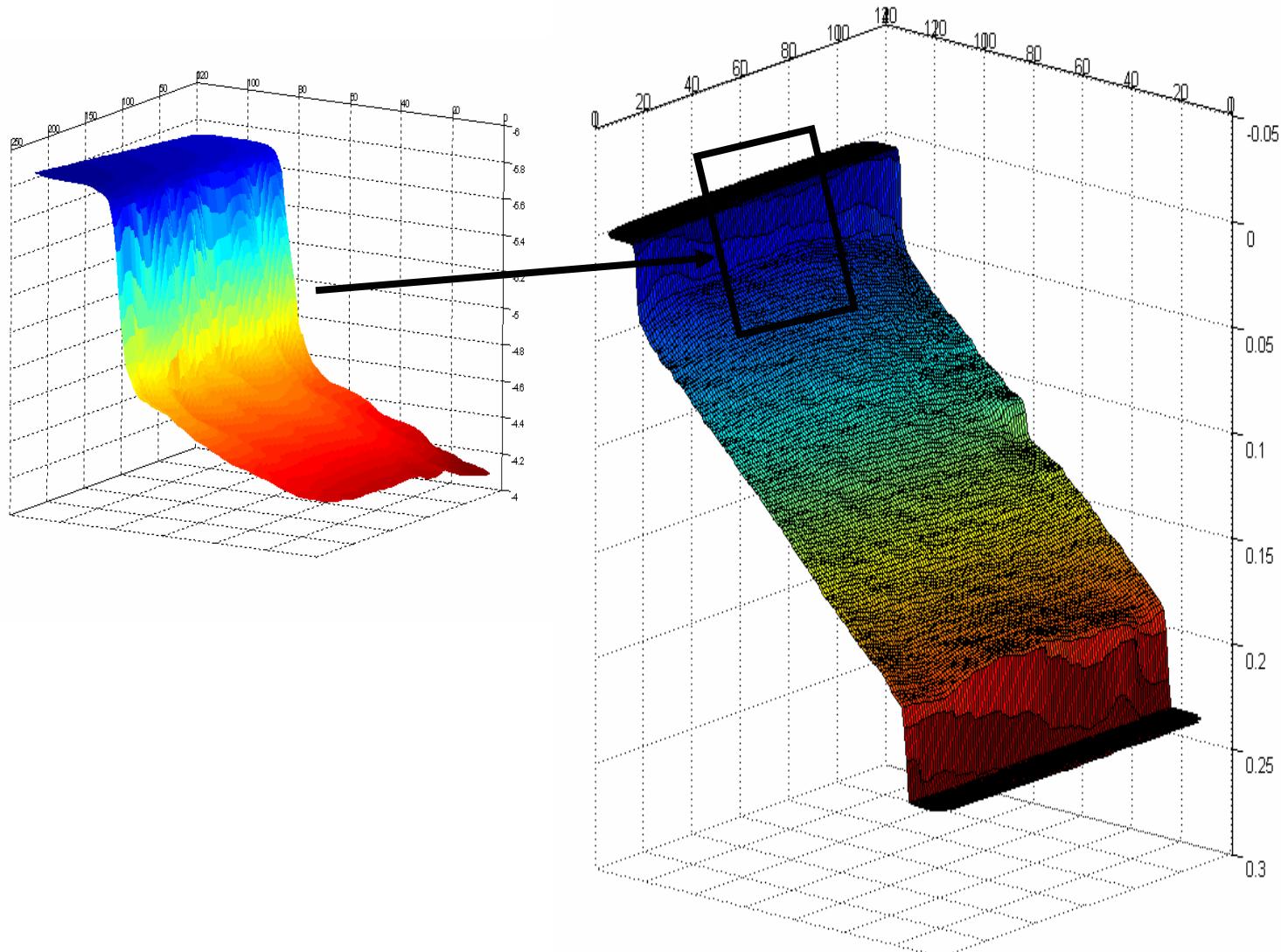
Face matching after deformation in x displacement (in mm)



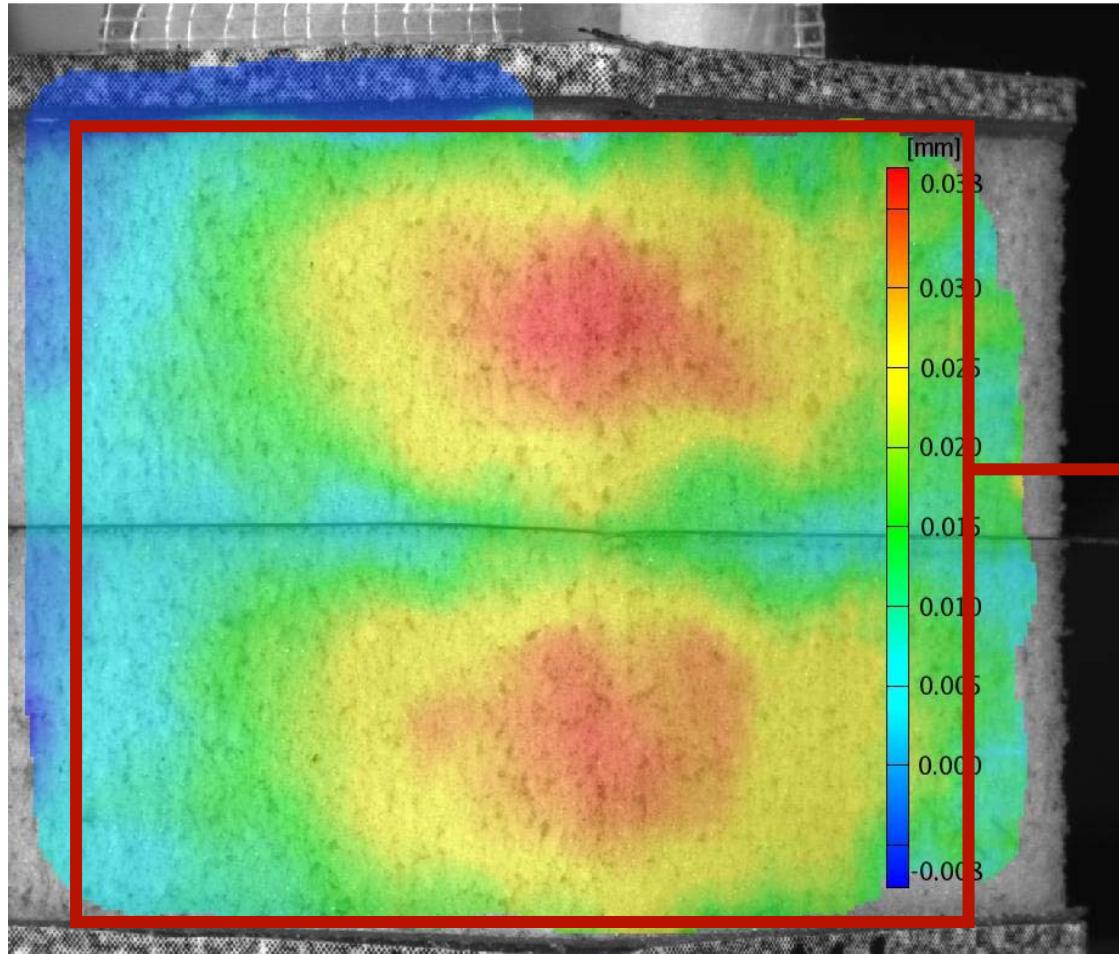
# Edge effect



# Edge effect



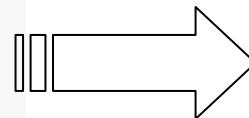
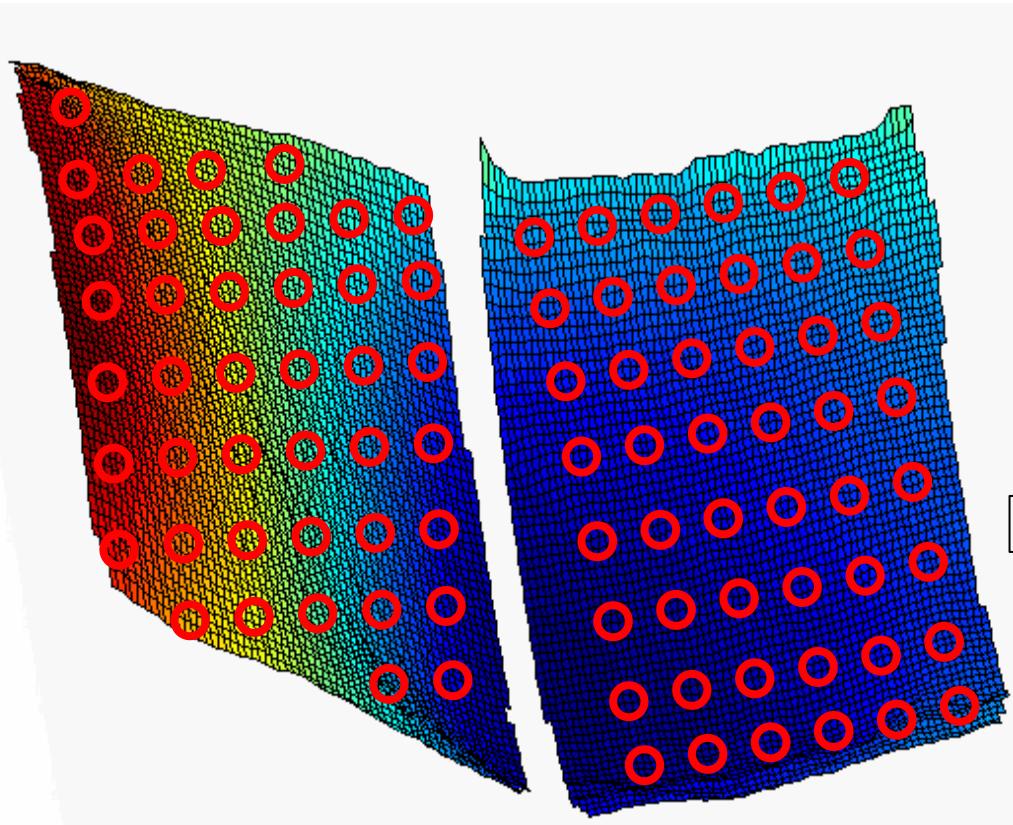
# Artificially introduced discontinuity



Out of picture plane displacement

Valid zone  
of focus

# Inverse estimation of elastic properties



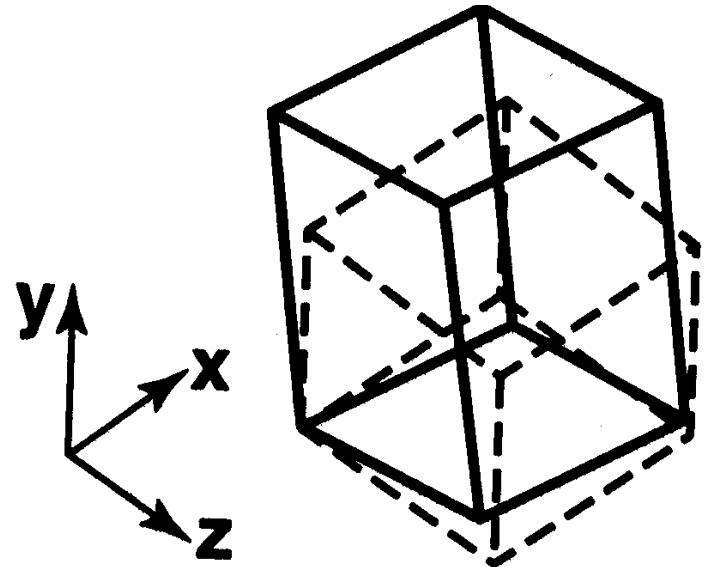
Approx 200  
points /cube

F.E model

Loads in 3  
directions

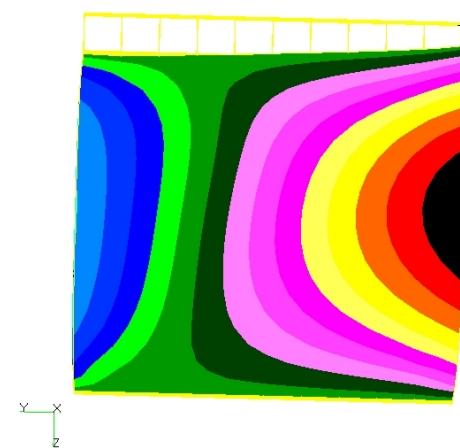
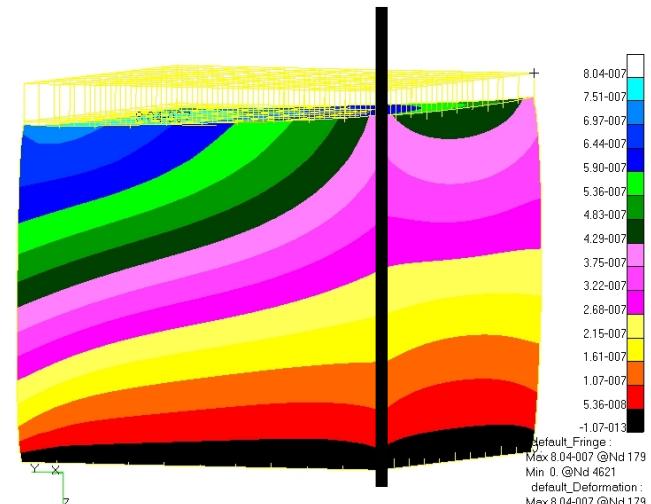
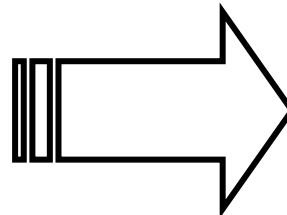
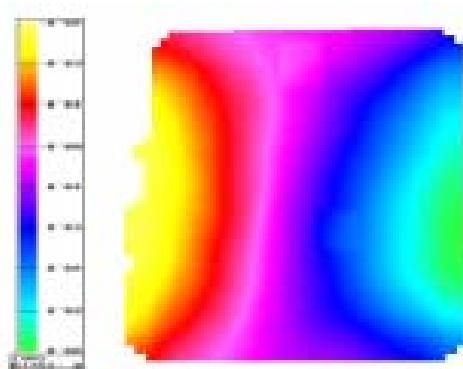
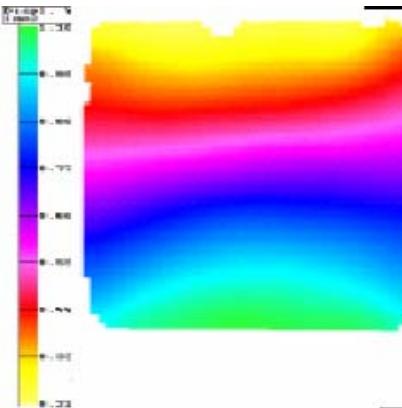
# Elastic material parameters

- In general anisotropic requires 21 constants.
- Here a **general orthotropic model** is assumed.
- This requires 9 independent constants and 3 angles of rotation (assuming body and material coordinate systems are different).



A total of ~600 points to fit a model of 12 parameters

# F.E Simulation & experimental



0.04-007  
7.51-007  
6.97-007  
6.44-007  
5.90-007  
5.36-007  
4.83-007  
4.29-007  
3.75-007  
3.22-007  
2.68-007  
2.15-007  
1.61-007  
1.07-007  
5.36-008  
-1.07-013  
Default\_Fringe :  
Max 0.04-007 @Nd 179  
Min 0. @Nd 4621  
default\_Deformation :  
Max 0.04-007 @Nd 179

8.01-008  
6.54-008  
5.07-008  
3.59-008  
2.12-008  
6.49-009  
-8.24-009  
-2.30-008  
-3.77-008  
-5.24-008  
-6.71-008  
-8.19-008  
-9.66-008  
-1.11-007  
-1.26-007  
-1.41-007  
Default\_Fringe :  
Max 8.01-008 @Nd 3179  
Min -1.41-007 @Nd 2190  
default\_Deformation :  
Max 8.04-007 @Nd 179

# Elastic material parameters

Possible (?) Hooke's matrix for Melamine

7.0734241e+05	4.1745677e+05	6.7939378e+05	2.8622851e+04	-2.2577011e+05	-1.8548001e+05
	6.6604861e+05	6.3696404e+05	8.7890445e+04	-1.3654600e+05	-1.7325758e+05
		1.7495901e+06	2.2418971e+05	-4.5269967e+05	-5.0137319e+05
			2.8930366e+05	-1.6297201e+04	-5.1279601e+04
				3.7323774e+05	2.5116848e+05
					3.5726698e+05

$$\boldsymbol{\sigma}_f^T = [\sigma_{11} \quad \sigma_{22} \quad \sigma_{33} \quad \sigma_{12} \quad \sigma_{13} \quad \sigma_{23}]$$

# Conclusion

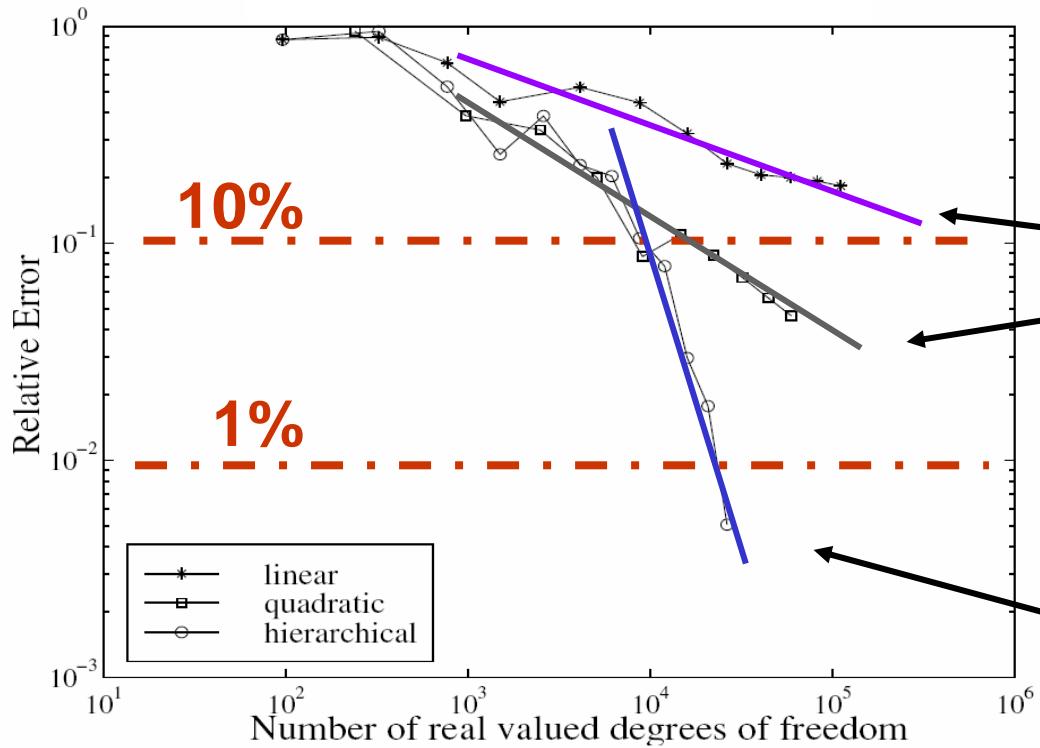
- Inverse estimation requires very high quality experimental data
- A methodology for precise characterization is under development
- Aiming at finding a static anisotropic elastic and fluid model of the foam
- Precise dynamic and acoustic model is under development

# Presentation Outline

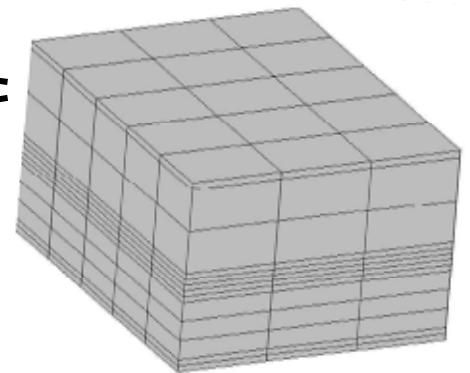
- Numerical design of automotive multilayer trim for low-mid frequencies
- Higher order FE solutions to Biot's equations with convergent results
- Lightweight layered trim components with solid, porous, viscoelastic materials
- Convergence for single & multilayer
- Influence of boundary conditions

# Numerical Simulation Summary

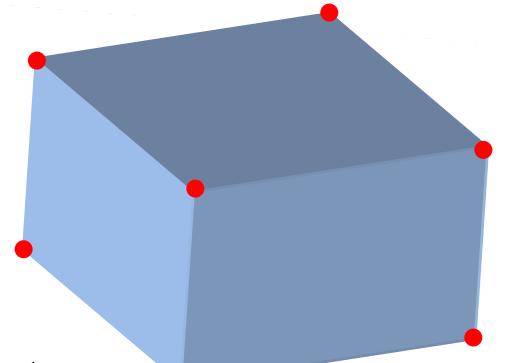
## Convergence of 3D Porous FE Solutions ( $u-U$ )



Single Block of  
Foam @ 190Hz



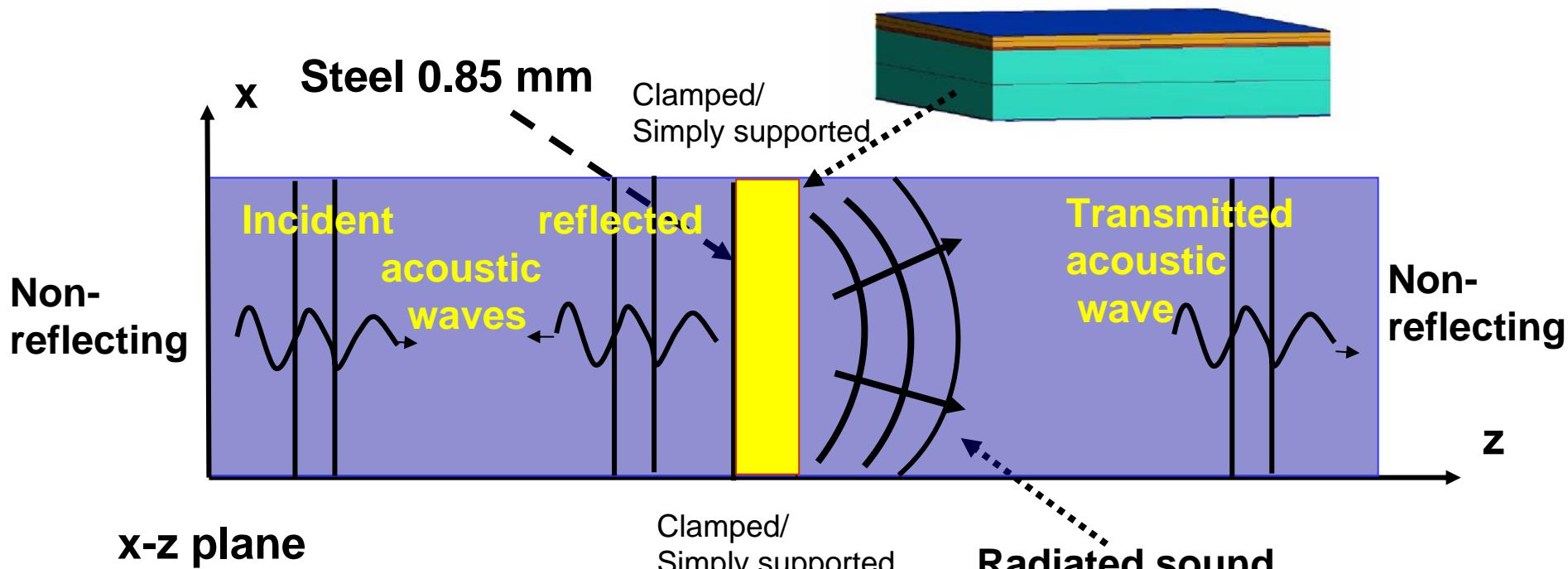
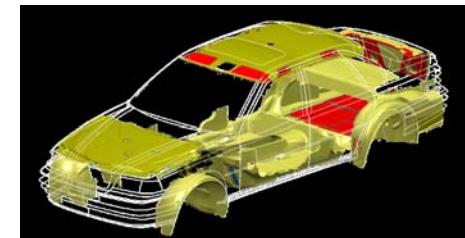
Hörlin et al & Rigobert et al



**Insufficient accuracy for linear and quadratic elements**  
**Remedy: Using higher order hierarchical elements**

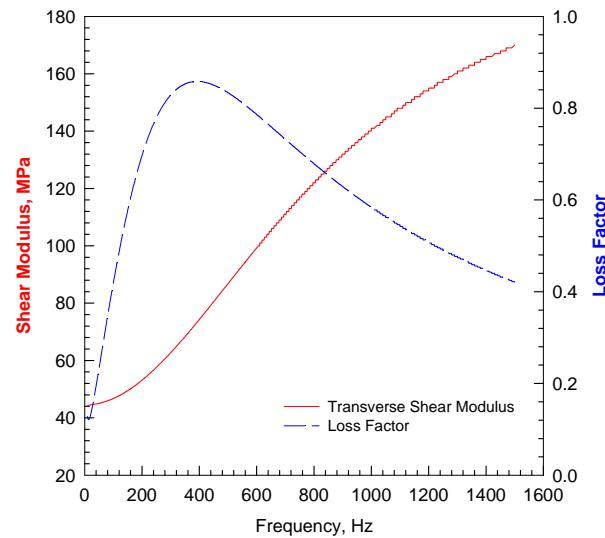
# 3D Numerical Design Problem

Representative, multilayer component, 32 + 5 mm

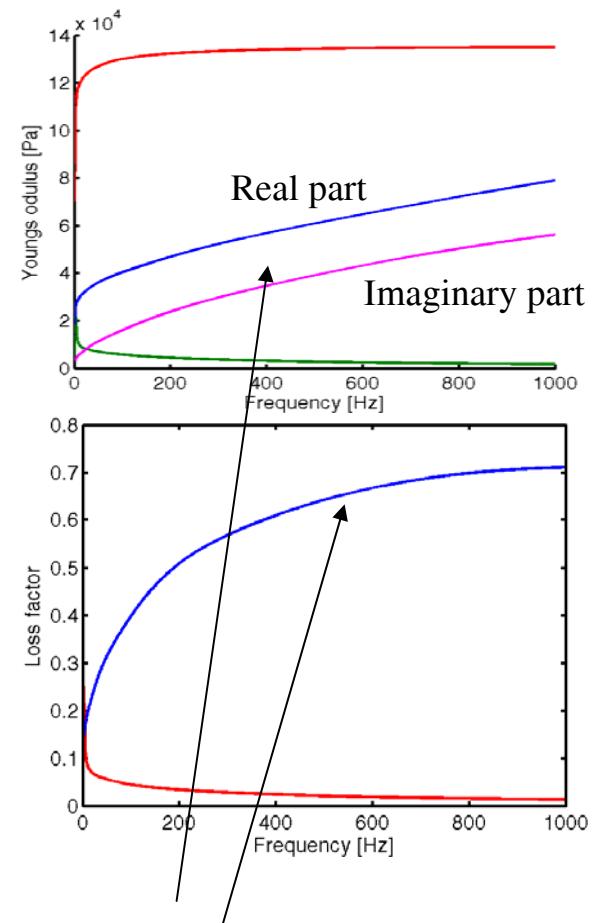
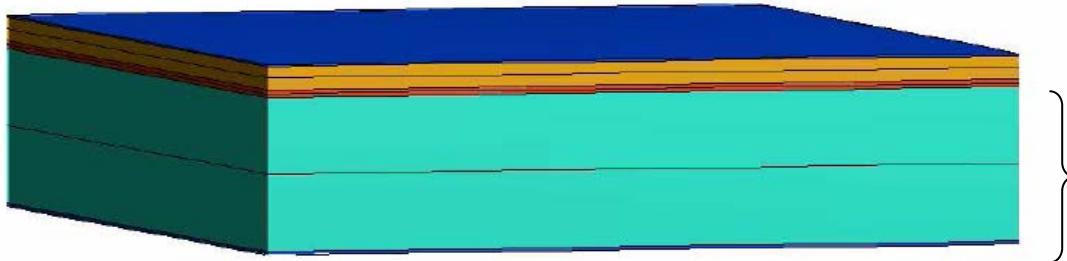


Cross dimensions  
400 mm x 500 mm

# Multilayer Trim Configuration



Visco-elastic barrier



Visco-elastic PU foam

# Multilayer Trim Configuration, cont'd

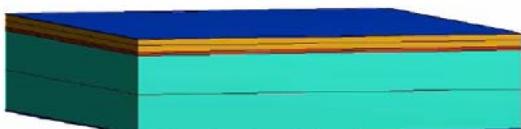
Evaluate convergence for increasingly complex

- layering
- boundary conditions
- Excitation through an acoustic wave
- Meshing:
  - One element over the surface
  - Two elements over the foam thickness
  - One element over the steel and barrier thicknesses

$L_2$ -norm

$$\sqrt{\int_{\Gamma} uu^* d\Gamma}$$

Sequence of convergence assessments @ 500 Hz



- Visco-elastic layer (rel. fast convergence)
- **Visco-elastic foam**
- **Visco-elastic foam + barrier on steel plate**

Fixed &  
Simply supported

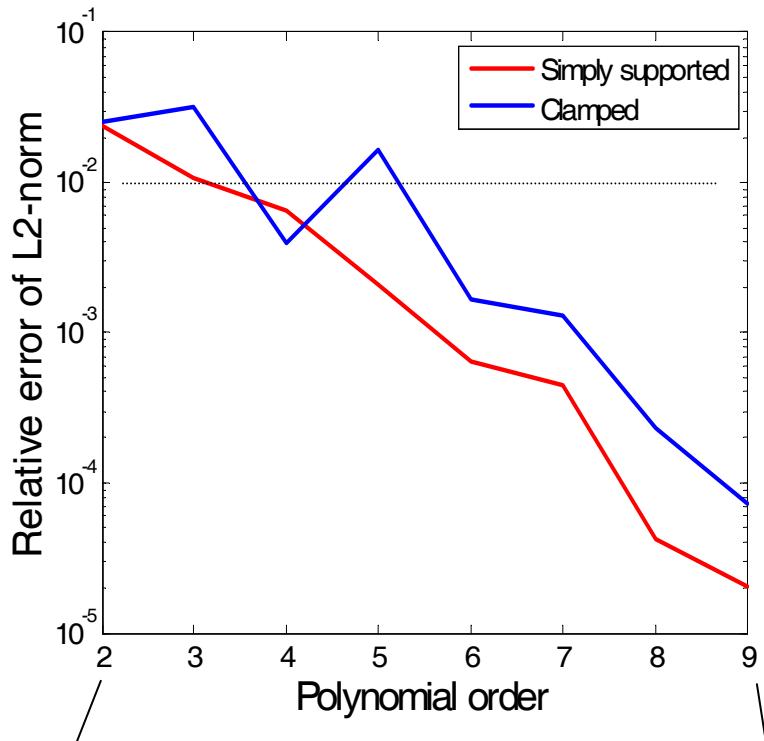
# Convergence in $L_2$ -norm (u-p)

Visco-elastic foam

$L_2$ -norm

$$\sqrt{\int_{\Gamma} uu^* d\Gamma}$$

Influence of boundary conditions

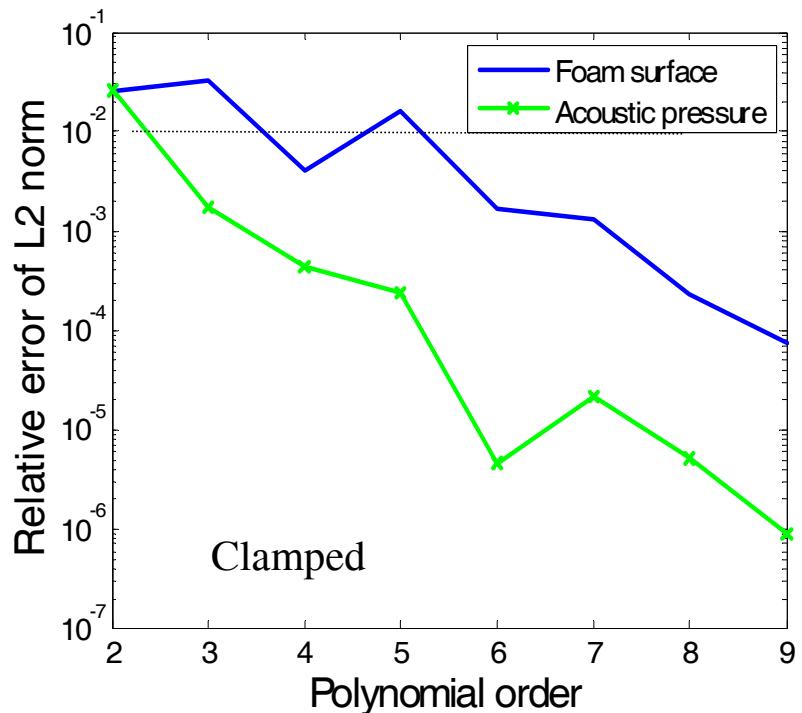


1300 dofs

13000 dofs

50000 dofs

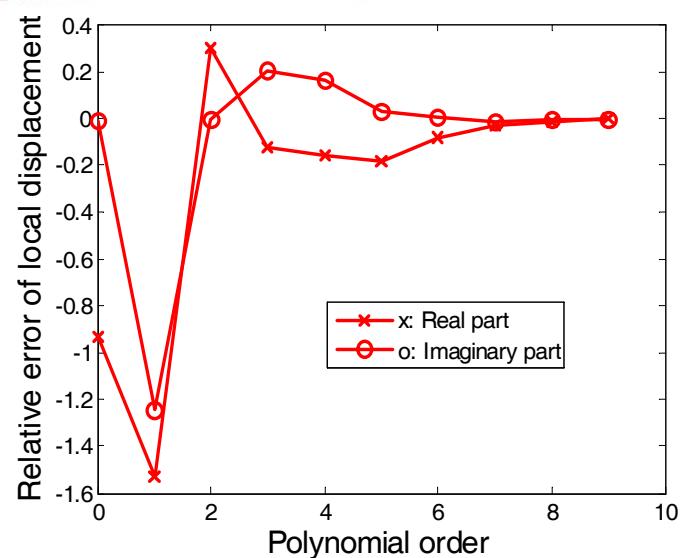
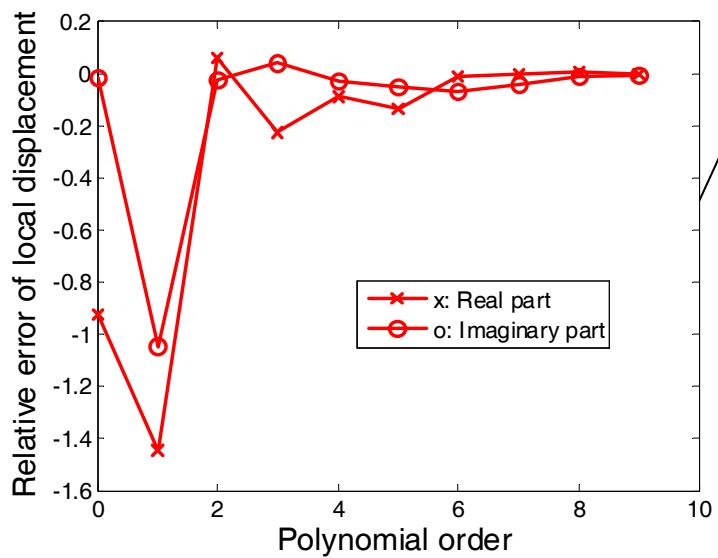
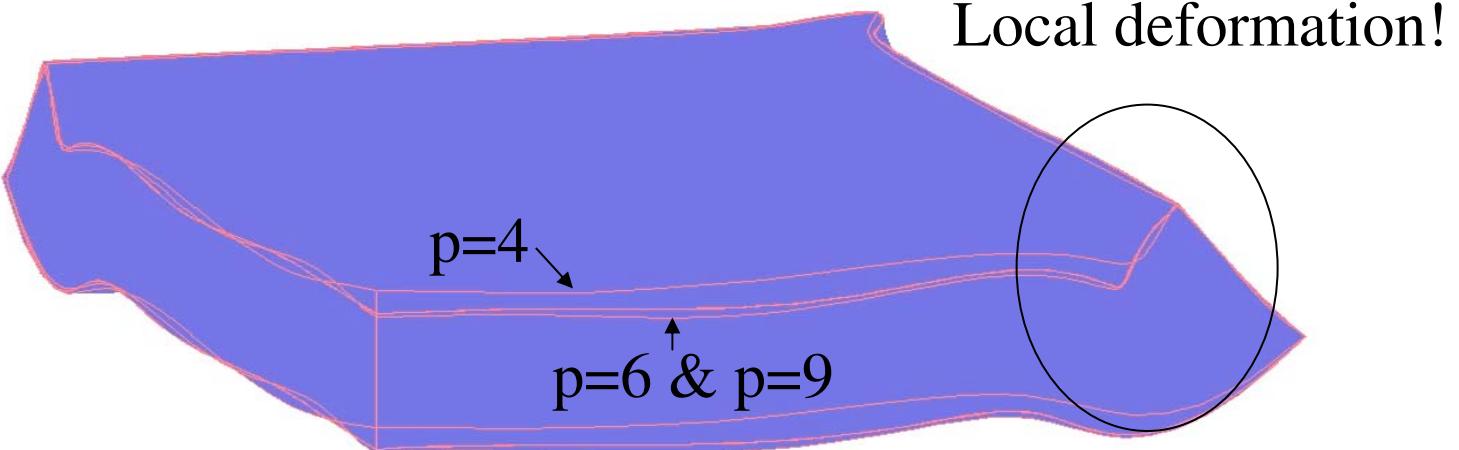
Deformation & pressure in far-field



Clamped

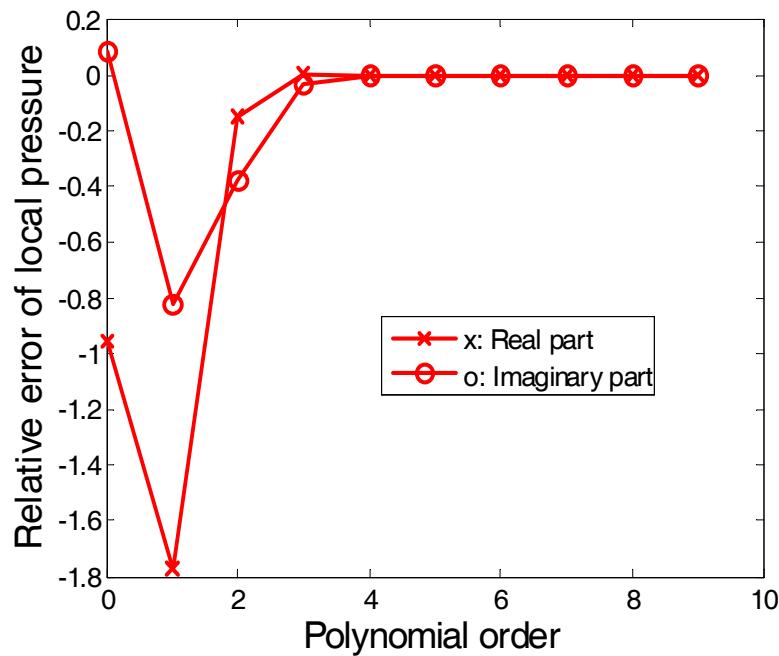
# Visco-elastic foam, simply supported

## Convergence in deformation ( $u-p$ )

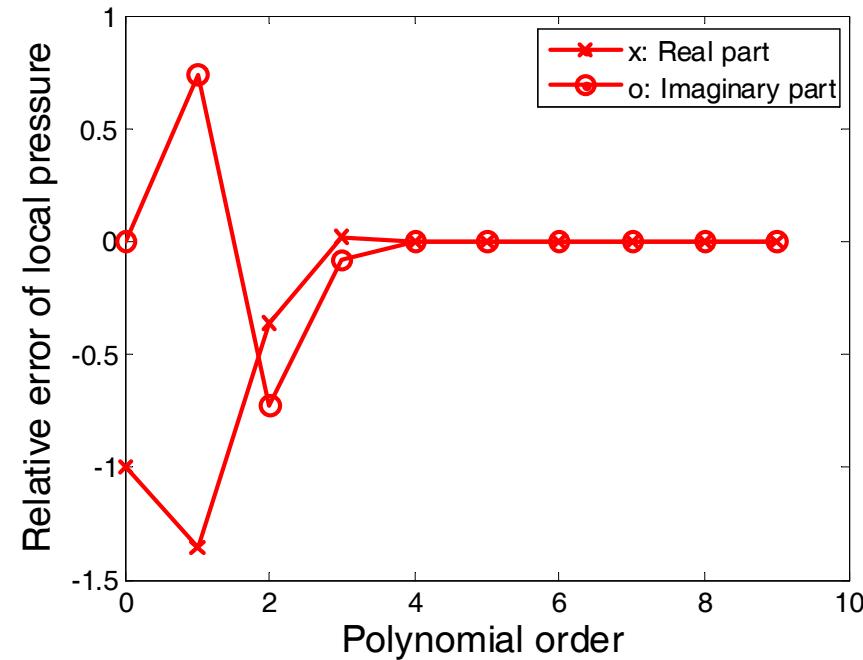


# Convergence in pressure (u-p)

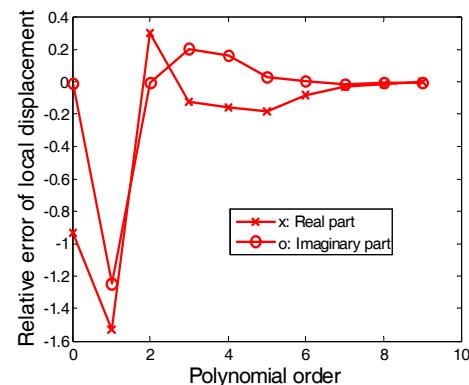
Pressure close to foam surface



Pressure in far-field

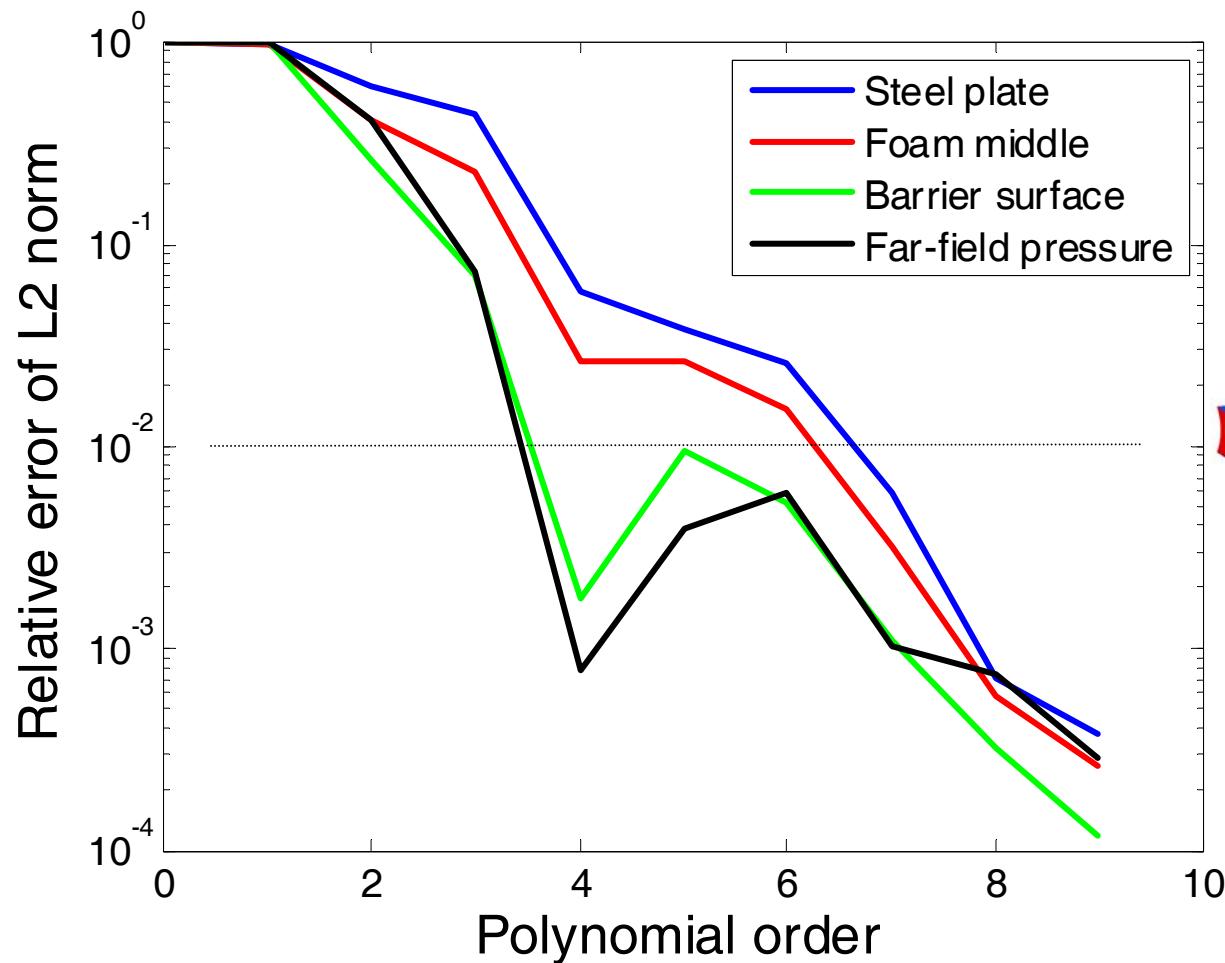


Visco-elastic foam, simply supported



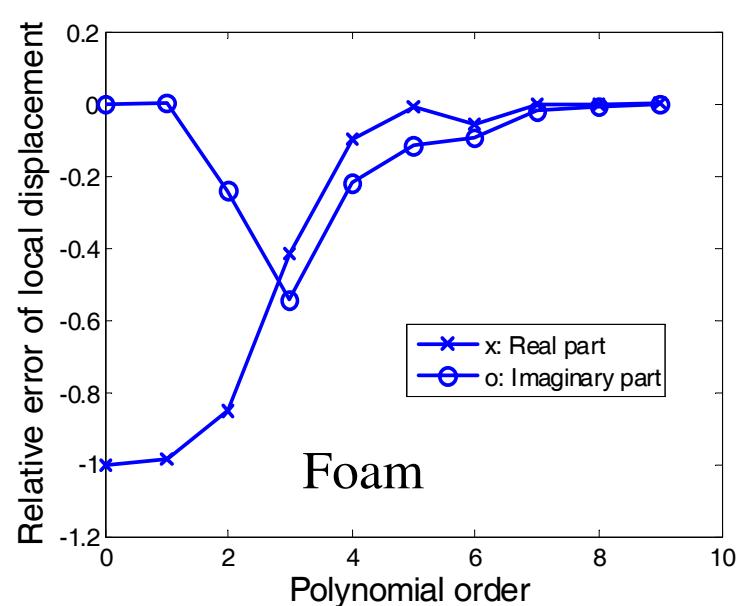
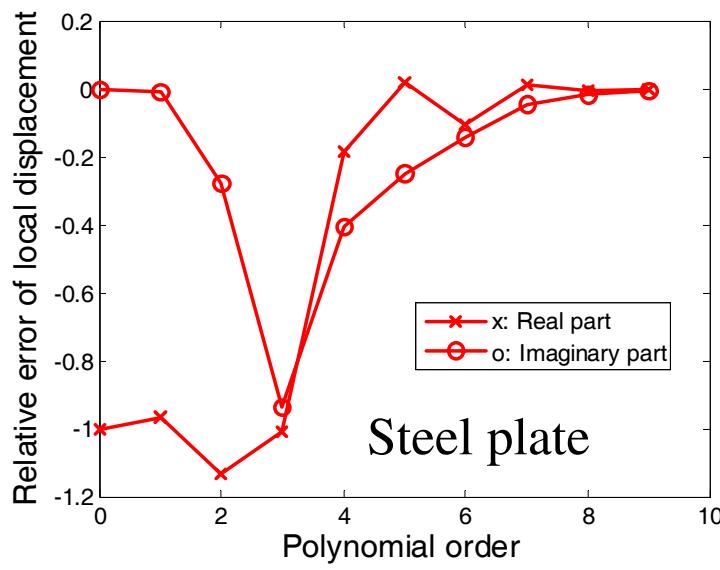
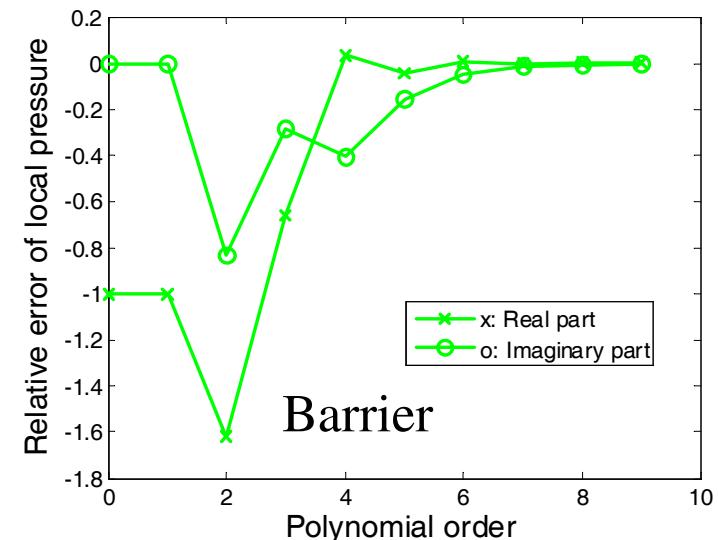
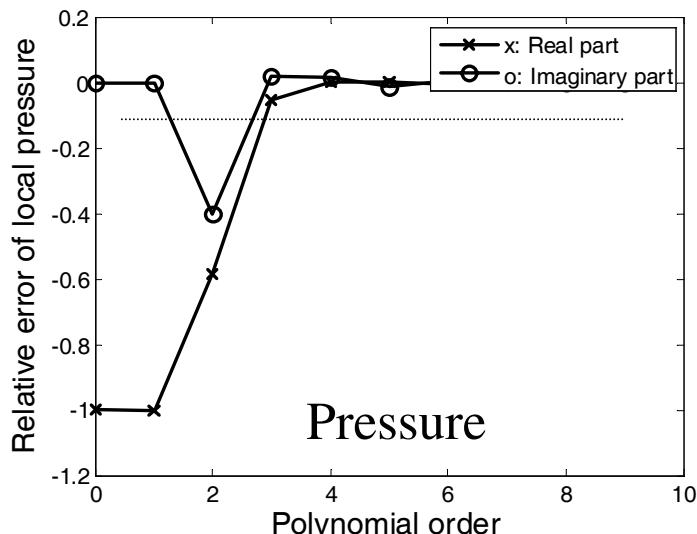
# Convergence in $L_2$ -norm ( $u-p$ )

Visco-elastic foam + barrier on steel, clamped



Steel+Visco-elastic foam + Barrier, clamped

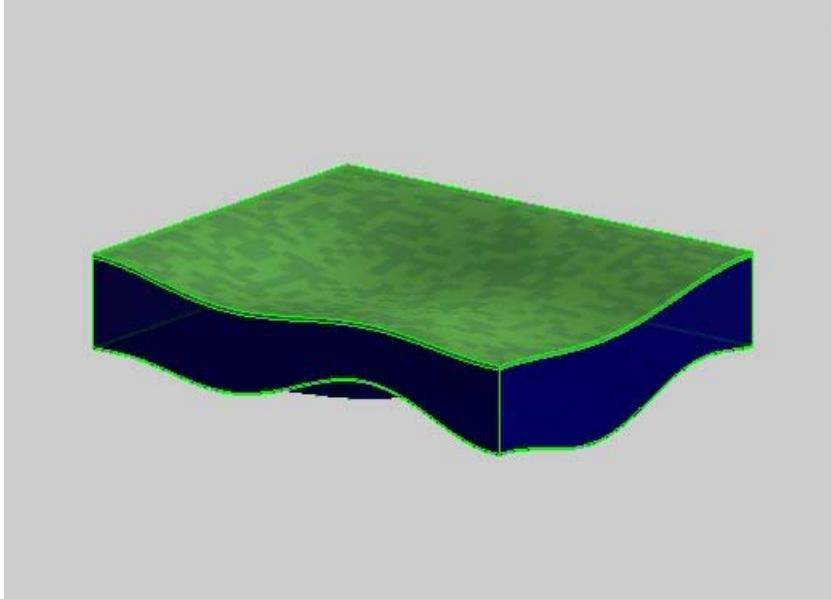
# Convergence in deformation ( $u-p$ )



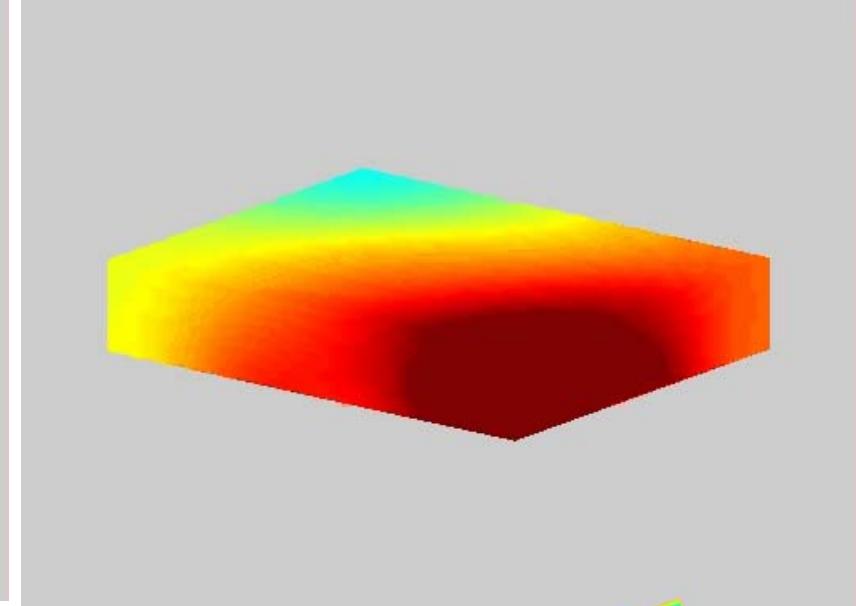
Steel+Visco-elastic foam + Barrier, clamped

# Deformations and Internal Pressures (u-p)

Deformation

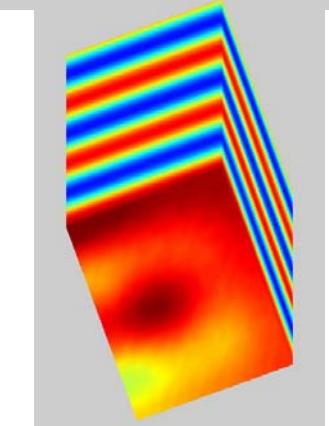


500 Hz



Pressure in foam

Transmitted pressure



# Concluding Remarks

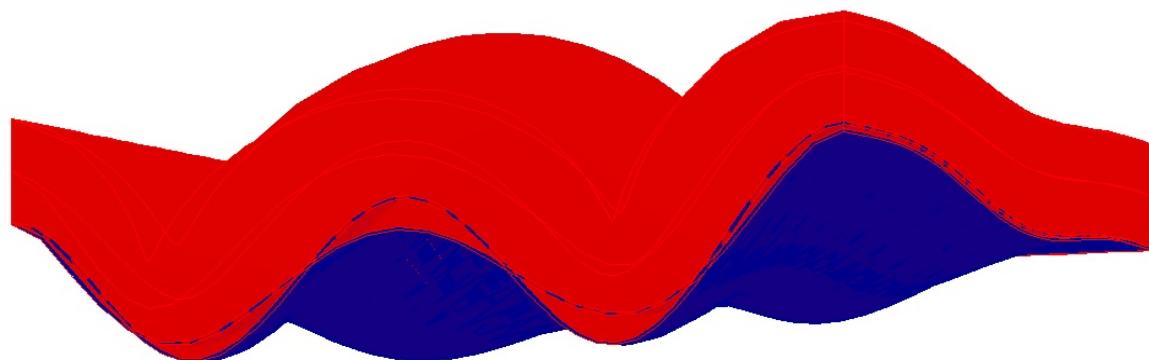
- Boundary conditions tends to slow down convergence for a single layer
- No substantial change in the condition number for multilayer configurations
- Pressure solution converges in general at lower p-levels (~2-3 lower)
- To reach an accuracy better than 1% of the surface average we need:
  - for a single foam layer p=6
  - for a multilayer sandwich p=7

for the foam
- To reach an accuracy better than 10% of point wise quantities we need:
  - for a single foam layer p=6-7
  - for a multilayer sandwich p=5-6

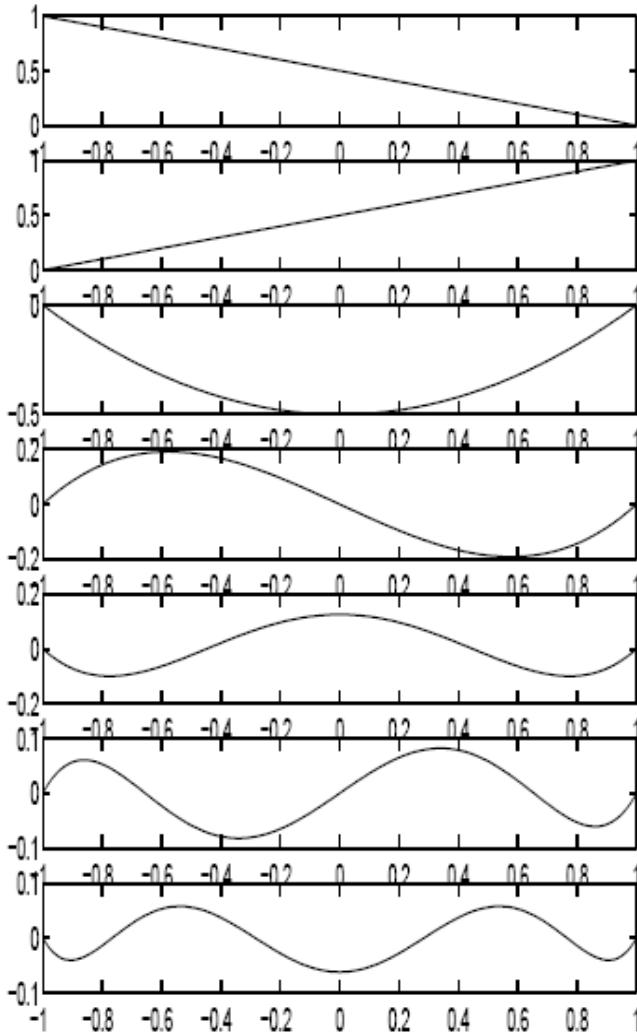
for the foam
- N.B. @ 500 Hz

# Convergence in deformation ( $u-p$ )

Visco-elastic foam on steel plate, clamped



# Hierarchical basis functions



$$w(\xi_1, \xi_2, \xi_3) = \sum_{l_1=1}^{p_1+2} \sum_{l_2=1}^{p_2+2} \sum_{l_3=1}^{p_3+2} c_{\{l_1, l_2, l_3\}} \phi_{\{l_1, l_2, l_3\}}(\xi_1, \xi_2, \xi_3)$$

$$\xi_1, \xi_2, \xi_3 \in [-1, 1]$$

$$\phi_{\{l_1, l_2, l_3\}}(\xi_1, \xi_2, \xi_3) = f_{l_1}(\xi_1) f_{l_2}(\xi_2) f_{l_3}(\xi_3)$$

(2)

$$f_l(\chi) \stackrel{\text{def}}{=} \begin{cases} \frac{1}{2}(1-\chi) & l=1 \\ \frac{1}{2}(1+\chi) & l=2 \\ \sum_{s=0}^{\text{int}(l/2)} \frac{(-1)^s (2l-2s-5)!!}{2^s s!(l-2s-1)!} \chi^{l-2s-1} & l \geq 3. \end{cases}$$

# Convergence in $L_2$ -norm

Visco-elastic layer

Deformation of VE layer

